

## Lecture 3: Groups of permutations and symmetries

A **permutation** of a finite set  $T$  is a *bijection* from  $T$  to  $T$ . This means that every element has a different image, and the image of the function is the whole set  $T$ . The permutations of a set form a group under **composition**.

The group of all permutations of a set of  $n$  elements is called the **symmetric group of degree  $n$**  and denoted  $S_n$ .

How the composition operation works: the example of  $S_3$ .

$S_3$ : the set of all permutations of  $\{1, 2, 3\}$

Take  $\sigma, \tau$  in  $S_3$

$\sigma$   
sigma

$\tau$   
tau

$$\sigma: \begin{array}{l} 1 \rightarrow 3 \\ 2 \rightarrow 1 \\ 3 \rightarrow 2 \end{array}$$

$$\tau: \begin{array}{l} 1 \rightarrow 2 \\ 2 \rightarrow 1 \\ 3 \rightarrow 3 \end{array}$$

$$\sigma = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix}$$

$$\tau = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} \quad (\text{Notation})$$

# Compositions

$\sigma \circ \tau$ :  $\sigma$  "after"  $\tau$

1	$\longrightarrow$	2	$\longrightarrow$	1
2	$\longrightarrow$	1	$\longrightarrow$	3
3	$\longrightarrow$	3	$\longrightarrow$	2

$\tau$   $\sigma$

$\sigma \circ \tau$ :  $1 \rightarrow 1$   
 $2 \rightarrow 3$   
 $3 \rightarrow 2$

$\sigma \circ \tau = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} \#$

$\tau \circ \sigma$

$\tau$  after  $\sigma$

$$\begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix}$$

$\tau$   $\sigma$

Note  $\tau \circ \sigma \neq \sigma \circ \tau$   $\sigma \circ \text{id} = \sigma$

Identity permutation:  $\text{id} = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix}$   $\text{id} \circ \sigma = \sigma$   
for any  $\sigma \in S_3$

Inverses Two permutations  $\sigma, \tau$  are inverses of each other if  $\sigma \circ \tau$  and  $\tau \circ \sigma$  are both equal to id.

The inverse of  $\sigma$ :

1	$\xrightarrow{\sigma}$	3
2	$\xrightarrow{\sigma}$	2
3	$\xrightarrow{\sigma}$	1

$\sigma^{-1}$

In "array notation"

$$\sigma = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix} \quad \sigma^{-1} = \begin{pmatrix} 3 & 2 & 1 \\ 1 & 2 & 3 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix}$$

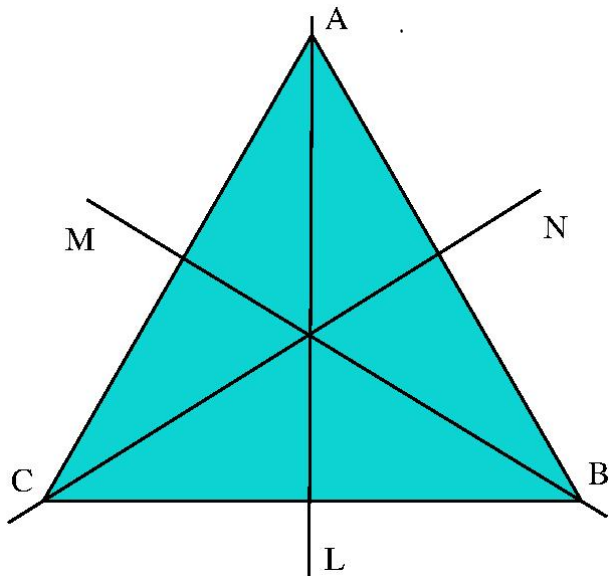
Example

$$Z = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}$$

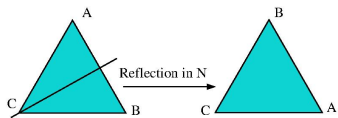
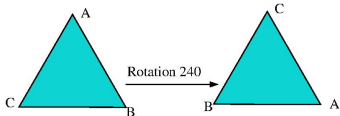
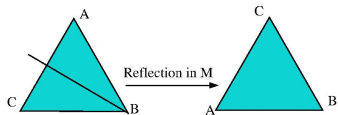
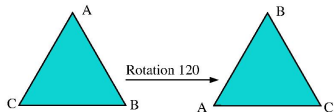
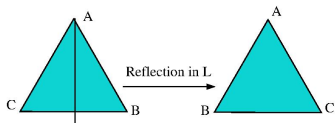
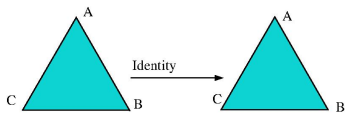
$$Z^{-1} = \begin{pmatrix} 2 & 3 & 1 \\ 1 & 2 & 3 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix}$$

Note  $Z^{-1} \neq Z$  in this case.

# The group of symmetries of the equilateral triangle



# Symmetries of the triangle

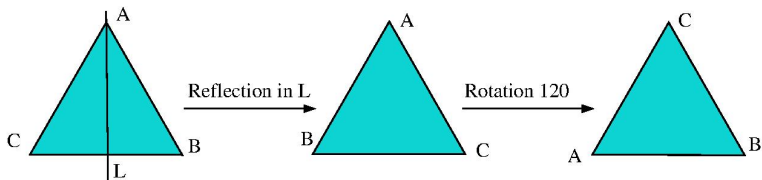


## The Group Operation in $D_6$

The group  $D_6$  of symmetries of the triangle has six elements.

$$D_6 = \{\text{id}, R_{120}, R_{240}, T_L, T_M, T_N\}.$$

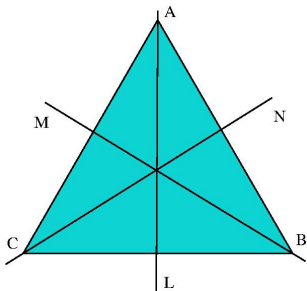
The group operation is composition, denoted by the symbol  $\circ$ .  $R_{120} \circ T_L$  means “ $R_{120}$  after  $T_L$ ”, the symmetry obtained by applying  $T_L$  first and then  $R_{120}$ . We can figure out which one it is by watching what happens to the vertices in this composition of symmetries.



Comparing the final position to the starting position, we see that

$$R_{120} \circ T_L = T_M.$$

## Group table for $D_6$



$\circ$	id	$R_{120}$	$R_{240}$	$T_L$	$T_M$	$T_N$
id	id	$R_{120}$	$R_{240}$	$T_L$	$T_M$	$T_N$
$R_{120}$	$R_{120}$	$R_{240}$	id	$T_M$	$T_N$	$T_L$
$R_{240}$	$R_{240}$	id	$R_{120}$	$T_N$	$T_L$	$T_M$
$T_L$	$T_L$	$T_N$	$T_M$	id	$R_{240}$	$R_{120}$
$T_M$	$T_M$	$T_L$	$T_N$	$R_{120}$	id	$R_{240}$
$T_N$	$T_N$	$T_M$	$T_L$	$R_{240}$	$R_{120}$	id

In general, the group of symmetries of the regular  $n$ -gon is denoted  $D_{2n}$  and called the **dihedral group of order  $2n$** . It has  $2n$  elements,  $n$  rotations (including the identity) and  $n$  reflections.



## Weekly Challenge 2

Like a polygon, a 3-dimensional object has a group of symmetries, which includes rotations and reflections. This week's challenge is to give a description of the rotational symmetries of the cube. How many are there? What are the axes about which rotational symmetries occur, and what the the angles of rotation?

