## 1.4 Leading Variables and Free Variables

Example 1.4.1 Find the general solution of the following system :



 $\overline{1}$ 

## Solution :

1. Write down the augmented matrix of the system :

Eqn I  
\nEqn II  
\n
$$
\begin{pmatrix}\n1 & -1 & -1 & 2 & 0 \\
2 & 1 & -1 & 2 & 8 \\
1 & -3 & 2 & 7 & 2\n\end{pmatrix}
$$
\n
$$
x_1 \quad x_2 \quad x_3 \quad x_4
$$

Note : This is the matrix of Example 1.2.4

2. Use Gauss-Jordan elimination to find a reduced row-echelon form from this augmented matrix. We have already done this in Examples 1.2.4 and 1.3.2 :-

RREF: 
$$
\begin{pmatrix} 1 & 0 & 0 & 2 & 4 \ 0 & 1 & 0 & -1 & 2 \ 0 & 0 & 1 & 1 & 2 \ \end{pmatrix}
$$

$$
x_1 \quad x_2 \quad x_3 \quad x_4
$$

This matrix corresponds to a new system of equations:

$$
x_1 + 2x_4 = 4 \t (A)
$$
  
\n
$$
x_2 - x_4 = 2 \t (B)
$$
  
\n
$$
x_3 + x_4 = 2 \t (C)
$$

Remark : The RREF involves 3 leading 1's, one in each of the columns corresponding to the variables  $x_1, x_2$  and  $x_3$ . The column corresponding to  $x_4$  contains no leading 1.

Definition 1.4.2 The variables whose columns in the RREF contain leading 1's are called leading variables. A variable whose column in the RREF does not contain a leading 1 is called a free variable.

So in this example the leading variables are  $x_1, x_2$  and  $x_3$ , and the variable  $x_4$  is free. What does this distinction mean in terms of solutions of the system? The system corresponding to the RREF can be rewritten as follows :

$$
x_1 = 4 - 2x_4 \t (A)
$$
  
\n
$$
x_2 = 2 + x_4 \t (B)
$$
  
\n
$$
x_3 = 2 - x_4 \t (C)
$$

i.e. this RREF tells us how the values of the leading variables  $x_1, x_2$  and  $x_3$  depend on that of the free variable  $x_4$  in a solution of the system. In a solution, the free variable  $x_4$ may assume the value of *any* real number. However, once a value for  $x_4$  is chosen, values are immediately assigned to  $x_1, x_2$  and  $x_3$  by equations A, B and C above. For example

- (a) Choosing  $x_4 = 0$  gives  $x_1 = 4 2(0) = 4$ ,  $x_2 = 2 + (0) = 2$ ,  $x_3 = 2 (0) = 2$ . Check that  $x_1 = 4$ ,  $x_2 = 2$ ,  $x_3 = 2$ ,  $x_4 = 0$  is a solution of the (original) system.
- (b) Choosing  $x_4 = 3$  gives  $x_1 = 4 2(3) = -2$ ,  $x_2 = 2 + (3) = 5$ ,  $x_3 = 2 (3) = -1$ . Check that  $x_1 = -2$ ,  $x_2 = 5$ ,  $x_3 = -1$ ,  $x_4 = 3$  is a solution of the (original) system.

Different choices of value for  $x_4$  will give different solutions of the system. The number of solutions is infinite.

The general solution is usually described by the following type of notation. We assign the *parameter* name t to the value of the variable  $x_4$  in a solution (so t may assume any real number as its value). We then have

$$
x_1 = 4 - 2t, \ x_2 = 2 + t, \ x_3 = 2 - t, \ x_4 = t; \ t \in \mathbb{R}
$$

or

General Solution :  $(x_1, x_2, x_3, x_4) = (4 - 2t, 2 + t, 2 - t, t); t \in \mathbb{R}$ 

This general solution describes the infinitely many solutions of the system : we get a particular solution by choosing a specific numerical value for t : this determines specific values for  $x_1, x_2, x_3$  and  $x_4$ .

Example 1.4.3 Solve the following system of linear equations :



Remark : The first three equations of this system comprise the system of equations of Example 1.4.1. The problem becomes : Can we find a solution of the system of Example 1.4.1 which is in addition a solution of the equation  $x_1 - x_2 + x_3 - x_4 = -6$ ?

Solution We know that every simultaneous solution of the first three equations has the form

$$
x_1 = 4 - 2t, \ x_2 = 2 + t, \ x_3 = 2 - t, \ x_4 = t,
$$

where  $t$  can be any real number. Is there some choice of  $t$  for which the solution of the first three equations is also a solution of the fourth? i.e. for which

$$
x_1 - x_2 + x_3 - x_4 = -6
$$
 i.e.  $(4 - 2t) - (2 + t) + (2 - t) - t = -6$ 

Solving for t gives

$$
4 - 5t = -6
$$
  

$$
\implies -5t = 10
$$
  

$$
\implies t = 2
$$

$$
t = 2: x_1 = 4 - 2t = 4 - 2(2) = 0; x_2 = 2 + t = 2 + 2 = 4; x_3 = 2 - t = 2 - 2 = 0; x_4 = t = 2
$$
  
Solution:  $x_1 = 0, x_2 = 4, x_3 = 0, x_4 = 2$  (or  $(x_1, x_2, x_3, x_4) = (0, 4, 0, 2)$ ).

This is the unique solution to the system in Example 1.4.3.

## Remarks:

1. To solve the system of Example 1.4.3 directly (without 1.4.1) we would write down the augmented matrix :

$$
\begin{pmatrix} 1 & -1 & -1 & 2 & 0 \ 2 & 1 & -1 & 2 & 8 \ 1 & -3 & 2 & 7 & 2 \ 1 & -1 & 1 & -1 & -6 \end{pmatrix}
$$

Check: Gauss-Jordan elimination gives the reduced row-echelon form :

$$
\left(\n\begin{array}{cccc}\n1 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 4 \\
0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 1 & 2\n\end{array}\n\right)
$$

which corresponds to the system

$$
x_1 = 0; \ x_2 = 4; \ x_3 = 0; \ x_4 = 2
$$

i.e. the unique solution is given exactly by the RREF. In this system, all four variables are leading variables. This is always the case for a system which has a unique solution : that each variable is a leading variable, i.e. corresponds in the RREF of the augmented matrix to a column which contains a leading 1.

2. The system of Example 1.4.1, consisting of Equations 1,2 and 3 of that in Example 1.4.3, had an infinite number of solutions. Adding the fourth equation in Example 1.4.3 pinpointed exactly one of these infinitely many solutions.