

Differential 0-forms in 1-variable

$$(p=0, n=1)$$

A differential 0-form in 1 variable is just a differentiable real valued function

$$\omega = f(x)$$

Examples

$$\omega = 3x - 4$$

$$\omega = 3x^2 + 4$$

$$\omega = \sin(x)$$

are differential 0-forms.

usually a differential 0-form is given in the context of some closed interval

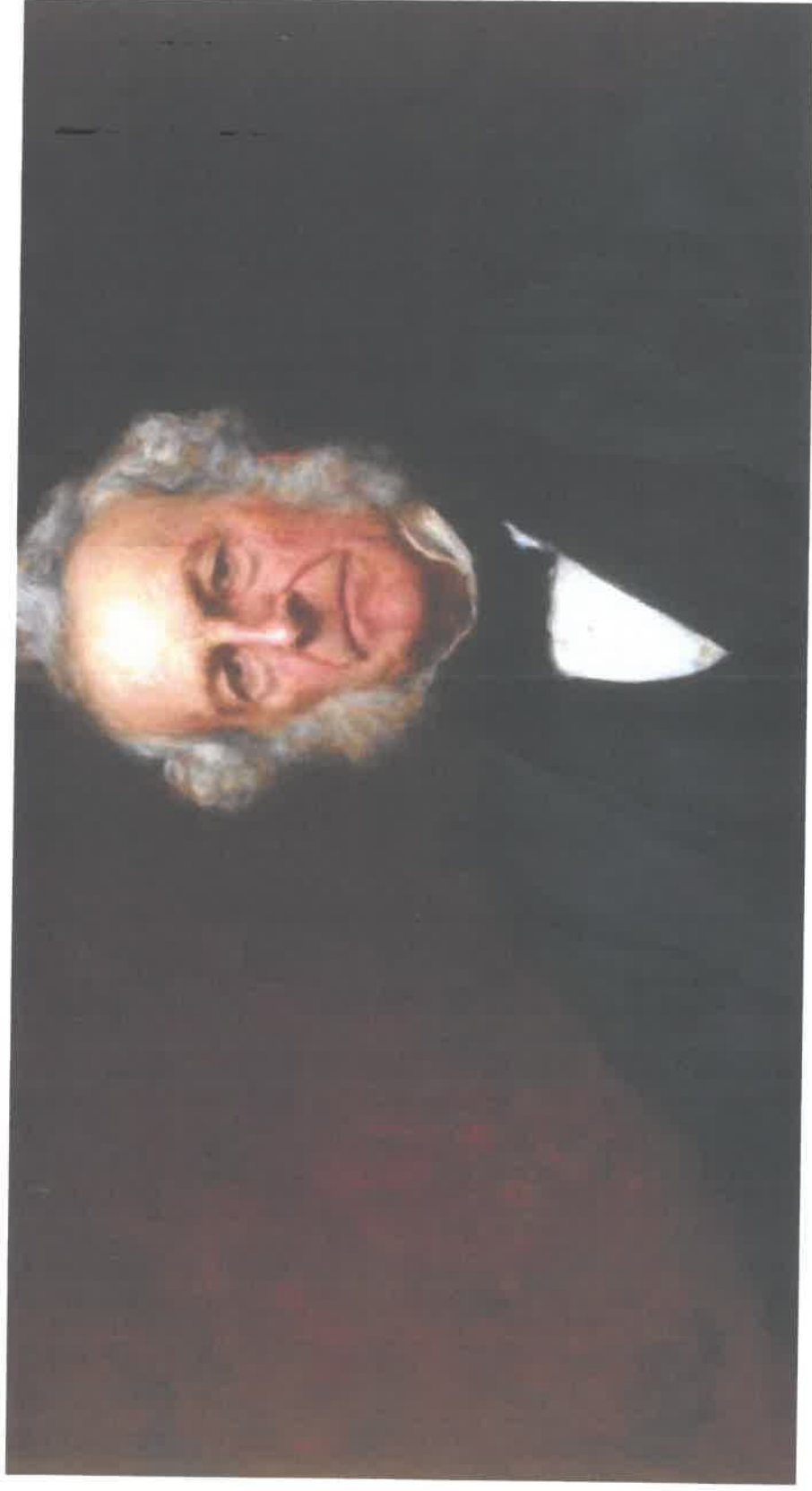
$$S = [a, b] \subseteq \mathbb{R}$$

or a union of closed intervals

$$S = [a_1, b_1] \cup [a_2, b_2] \cup \dots \cup [a_p, b_p].$$

Sir George Stokes

1819 - 1903



William Thomson (Lord Kelvin)

1824 — 1907



9 Barton Street,
Westminster
July 2, 1850

MY DEAR STOKES

As I have not a copy of your paper on the Equil. & Motion of Elastic Solids, nor any other work of reference for the purpose, by me, I shall be much obliged by your sending me the *equations of equil^m* of (an) a non crystalline elastic solid under the action of any forces, and the formulae for the mutual actions betw. any two contiguous portions of the body. I have been trying but as yet without success, to make out something about the integration of the equations for the case of a solid of any form, with each point of its surface displaced to a given extent & in a given direction from its natural position. I think I see how it can be done when the solid is a rectangular parallelepiped, but not in a very inviting way. It was reading your paper on diffraction on my way from Cambridge that made me take up the subject again.

Do you know that the condition that $\alpha dx + \beta dy + \gamma dz$ may be the diff^d of a function of two indep^t variables for all points of a surface is

$$l \left(\frac{d\beta}{dz} - \frac{d\gamma}{dy} \right) + m \left(\frac{d\gamma}{dx} - \frac{d\alpha}{dz} \right) + n \left(\frac{d\alpha}{dy} - \frac{d\beta}{dx} \right) = 0?$$

I made this out some weeks ago with ref^{ce} to electromagnetism. With ref^{ce} to an elastic solid, the condⁿ may be expressed thus – the resultant axis of rotation at any point of the surface must be perp^r to the normal.

Your's very truly
WILLIAM THOMSON

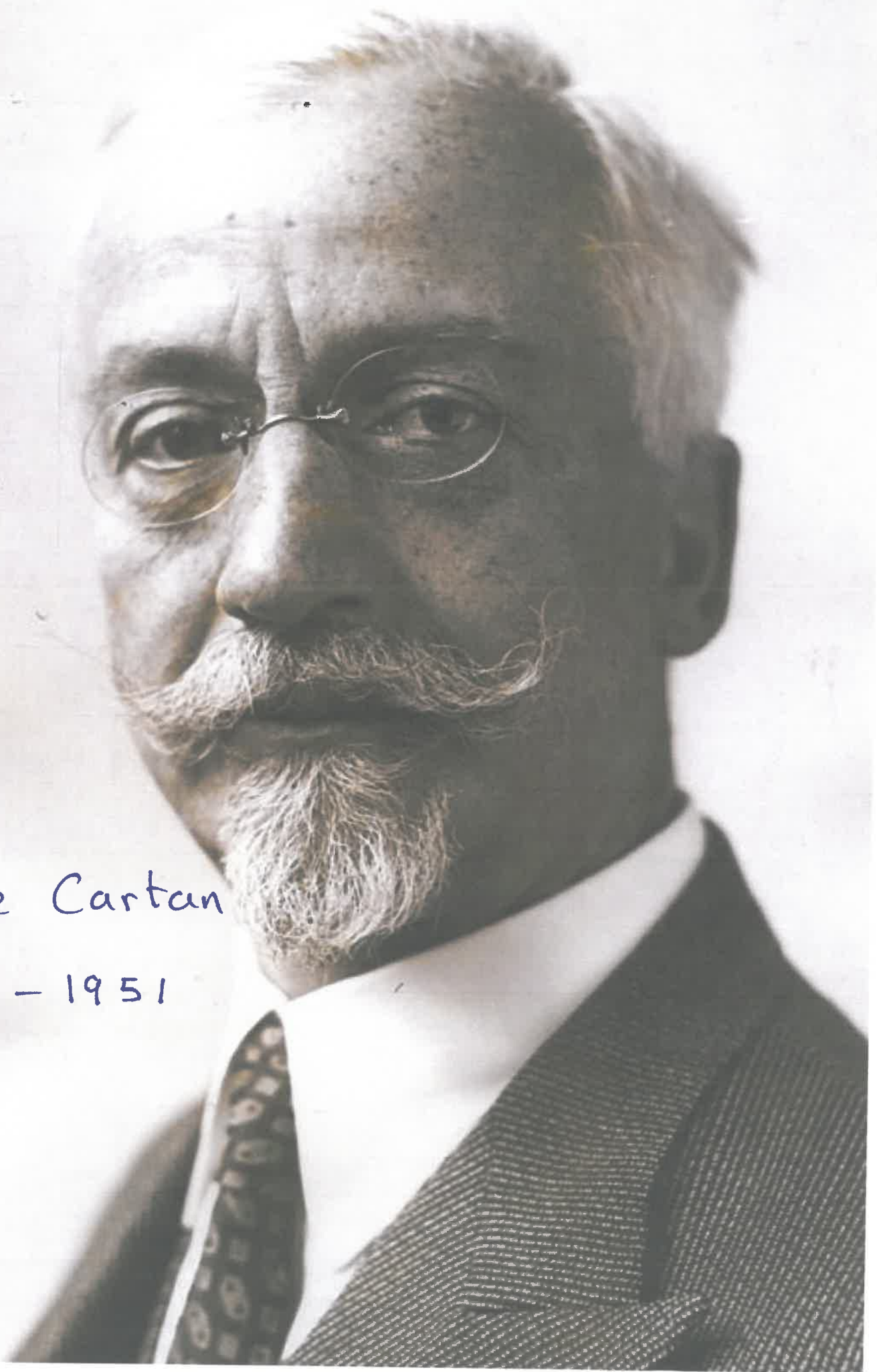
P.S. The following is also interesting, & is of importance with reference to both physical subjects.

$$\int (\alpha dx + \beta dy + \gamma dz) = \pm \iint \left\{ l \left(\frac{d\beta}{dz} - \frac{d\gamma}{dy} \right) + m \left(\frac{d\gamma}{dx} - \frac{d\alpha}{dz} \right) + n \left(\frac{d\alpha}{dy} - \frac{d\beta}{dx} \right) \right\} dS$$

where l, m, n denote the dirⁿ cosines of a normal through any el^t dS of a (limited) surface; & the integⁿ in the sec^d member is performed over a portion of this surface bounded by a curve round w^h the intⁿ in the 1st member is performed.

Sir William Rowan Hamilton
1805 - 1865





Élie Cartan

1869 - 1951

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Harold M. Edwards

Advanced Calculus: A Differential Forms Approach

$$\int_S d\omega = \int_{\partial S} \omega$$

Birkhäuser

July 2, 1850

My dear Stokes

As I have not
my from paper

in Eng. & last
elastic solids,

any other
reference for

purpose, by me
be much oblige

never in a
a revolution
in a person

may it was ready
a direct

of the following is also interesting
for... instances with reference to
both physical subjects.

$$\int (x dx + y dy + z dz) = \frac{1}{2} [x^2 + y^2 + z^2]$$

which may be used to find the line integral
through any ell. of a surface, the integral
on the last member is performed over a portion

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A CHAPMAN & HALL BOOK

Michael Spivak

CALCULUS

ON

MANIFOLDS

Yours very truly

William Thomson

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We only require ω to be differentiable on S .

Example

$$\omega = |x|$$

is a differential 0-form on
 $S = [1, 1000]$.

Clearly ω is not a differential
0-form on

$$S = [-1, 1]$$

Terminology

I'll say 0-form instead of
differential 0-form.

For $a < b \in \mathbb{R}$ we write

$$[a, b] = \{x \in \mathbb{R} : a \leq x \leq b\}$$

and we picture this as



The arrow is an orientation that specifies the direction of travel for a to b .

for $a < b \in \mathbb{R}$ we write

$$[b, a] = \{x \in \mathbb{R} : a \leq x \leq b\}$$

and picture this as



We say that $[a, b]$ and $[b, a]$ are oriented intervals.

Example $S = [2, 1] \cup [3, 4] \cup [6, 5]$



The boundary of the oriented interval $S = [a, b]$ is the set

$$\partial S = \{a, b\}$$

the set consisting of two points, the initial point a and final point b .

Example

$$S = [2, 1] \cup [3, 4] \cup [6, 5]$$

$$\partial S = \{1, 2, 3, 4, 5, 6\}.$$

Terminology we'll say that

$S = [a, b]$ is 1-dimensional,

and that the boundary is

0-dimensional.

Definition Given a 0-form

$$\omega = F(x)$$

on an oriented interval

$$S = [a, b]$$

we define

$$\int_{\partial S} \omega = F(b) - F(a).$$

Example Integrate the differential

0-form

$$\omega = 3x^2 + 4$$

over the boundary of the oriented interval

$$S = [2, 1].$$

Soln

$$\begin{aligned} \int_{\partial S} \omega &= \omega(1) - \omega(2) \\ &= 3(1^2) + 4 - (3(2^2) + 4) \\ &= -9. \end{aligned}$$