

Yesterday: we checked that

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2, (x, y) \mapsto (3x + 7y, 2x + 5y)$$

is linear. i.e.

$$\bullet T(P + Q) = T(P) + T(Q)$$

$$\bullet T(\lambda P) = \lambda T(P) \quad \lambda \in \mathbb{R}$$

Note:

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2, (x, y) \mapsto (3x + 7y, 2x + 5y)$$

can be represented as matrix multiplication

$$\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} 3 & 7 \\ 2 & 5 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3x + 7y \\ 2x + 5y \end{pmatrix}$$

We say that

$$\begin{pmatrix} 3 & 7 \\ 2 & 5 \end{pmatrix}$$

represents the linear transformation T .

Theorem Any linear transformation

$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ can be represented
by a matrix.

Proof Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be any linear transformation.

Well

$$T(1 \ 0) = (a \ c)$$

$$T(0 \ 1) = (b \ d)$$

$$T(x \ y) = T(x(1,0) + y(0,1))$$

by
linearity of T $\left\{ \begin{array}{l} = T(x(1,0)) + T(y(0,1)) \\ = xT(1,0) + yT(0,1) \end{array} \right.$

$$= x(a \ c) + y(b \ d)$$

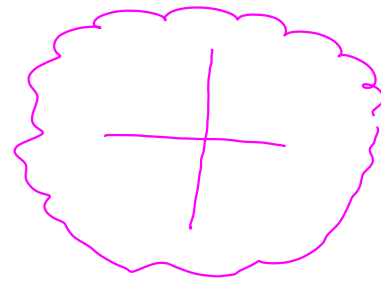
$$= (xa, xc) + (yb, yd)$$

$$= (ax+by, cx+dy).$$

Now

$$\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} ax+by \\ cx+dy \end{pmatrix}$$

Q.E.D

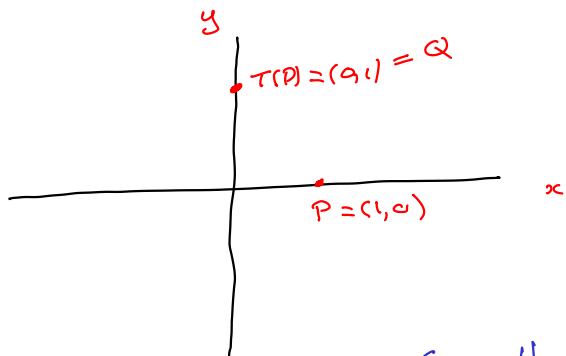


$$x(1,0) = (x,0)$$

Facts (about linear transformations of the plane)

- Any reflection in a line through the origin is linear.
- Any rotation of the plane about the origin is linear.
- Any composite of linear transformations is linear.

Example Find the matrix representing a reflection in the y -axis, followed by a clockwise rotation of $\frac{5\pi}{2}$ radians about the origin.



$$T(1, 0) = (0, 1)$$

$$T(0, 1) = (1, 0)$$

So the matrix of T
is

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

Theorem Let

$$S: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \quad \text{and} \quad T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

be linear transformations
represented by matrices A and B .

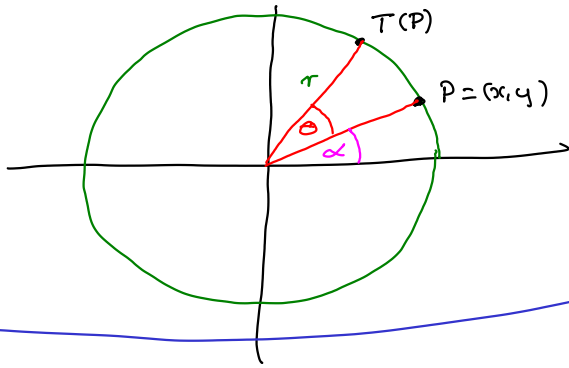
Then the linear transformation

$$S \circ T: \mathbb{R}^2 \rightarrow \mathbb{R}^2, \quad v \mapsto S(T(v))$$

is represented by the

matrix AB .

Consider an anticlockwise rotation T_θ of the plane about the origin through an angle θ . What matrix represents this transformation?



$$\text{If } P = (x, y) = (r \cos(\alpha), r \sin(\alpha))$$

Then

$$T(P) = (r \cos(\alpha + \theta), r \sin(\alpha + \theta))$$

$$= r (\cos(\alpha + \theta), \sin(\alpha + \theta))$$

$$\begin{aligned} T(P) &= r (\cos \alpha \cos \theta - \sin \alpha \sin \theta, \sin \alpha \cos \theta + \sin \theta \cos \alpha) \\ &= (x \cos \theta - y \sin \theta, y \cos \theta + x \sin \theta) \end{aligned}$$

So

$$T(P) = \begin{pmatrix} x \cos \theta - y \sin \theta \\ y \cos \theta + x \sin \theta \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

matrix of anticlockwise rotation about the origin through an angle θ .