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- Fundamental Units are
MASS, LENGTH, TIME

All physical quantities can be obtained by combining the fundamental units.

- Notation: ϕ physical quantity $\Rightarrow [\phi]$ its dimensions

We will denote by:

- M = dimension of mass (1kg, ... in the SI int. sys. units)
- L = dimension of length (1m in the SI)
- T = dimension of time

- Derived Quantities:

- Examples:
- $[\text{area}] = L^2$
 - $[\text{volume}] = L^3$
 - $[\text{velocity}] = LT^{-1}$
 - $[\text{acceleration}] = LT^{-2}$
 - $[\text{force}] = MLT^{-2}$ ($F = ma$)
 - $[\text{work}] = ML^2T^{-2}$ ($W = \underline{F} \cdot \underline{s}$)
 - $[\text{power}] = ML^2T^{-3}$ ($P = dW/dt$)

Thus we see that every derived variable appears in the form

$$[Q] = M^a L^b T^c \quad (\text{say } [\text{area}] = M^0 L^2 T^0)$$

↑ any physical quantity

- Important definition:

Π is a DIMENSIONLESS variable if $[\Pi] = M^0 L^0 T^0 = 1$

↑ Π is the capital letter π of the Greek alphabet

Example of dimensionless variables:

- Strain: $\epsilon = \frac{\Delta l}{l} = \frac{\text{variation of length}}{\text{length}}$ $[\epsilon] = 1$
- Angles: $\theta = \frac{s}{r} = \frac{\text{arc length}}{\text{radius}}$ $[\theta] = 1$

■ Buckingham's Theorem (also known as Π -theorem)



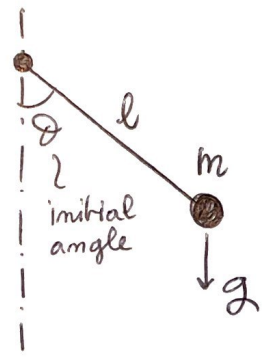
-----> Suppose it's governed by a physical law
 $F(Q_1, \dots, Q_n) = 0$ (*)
 where Q_1, \dots, Q_n are the involved variables.

Then denote by k the number of physical dimensions involved in the problem. Π -theorem then says that you can reformulate (*) as

$$\hat{F}(\Pi_1, \dots, \Pi_p) = 0 \quad p = n - k \leq n$$

where ~~parameters~~ Π_1, \dots, Π_p are DIMENSIONLESS VARIABLES.

•) Example: Simple Pendulum. Find the period τ of the oscill.



- involved variables: \sim the Q_i
 (τ, l, g, m, θ) $n = 5$
- fundamental physical dimensions:
 $[\tau] = T$ we see that all
 $[l] = L$ M, L, T
 $[g] = LT^{-2}$ are involved, thus
 $[m] = M$
 $[\theta] = 1$ $r = 3$

Then Π -Theorem secures that a law:

$$F(\tau, l, m, g, \theta) = 0$$

may be EQUIVALENTLY recast as

$$\hat{F}(\Pi_1, \Pi_2) = 0 \quad (\text{since } p = n - k = 5 - 3 = 2)$$

in terms of only TWO dimensionless variables Π_1, Π_2 .

How to find Π_1, Π_2 ? Assume that

$$\Pi = \tau^a l^b g^c m^d \vartheta^e$$

and impose $[\Pi] = 1$. So it's already dimless!

$$[\Pi] = T^a L^b (LT^{-2})^c M^d \vartheta^e = M^d L^{b+c} T^{a-2c} = M^0 L^0 T^0$$

we get the system:

$$\begin{cases} d=0 \\ b+c=0 \\ a-2c=0 \end{cases}$$

3 EQUATIONS for 4 UNKNOWNs
it would admit $\infty^{(4-3)} = \infty^1$ solutions

Take for example c as a parameter (that is, treat c as if it's fixed) then

$$\begin{cases} b=-c \\ a=2c \end{cases} \Rightarrow \Pi = \tau^{2c} l^{-c} g^c m^0 \vartheta^c = \left(\frac{\tau^2 g}{l}\right)^c \vartheta^c$$

Since at this point we know there are 2 dimless var, we thus obtain them by setting:

$$\begin{cases} c=1, e=0 : \Pi_1 = \frac{\tau^2 g}{l} \\ c=0, e=1 : \Pi_2 = \vartheta \end{cases} \quad (\text{CHECK THEY ARE DIMENSIONLESS!})$$

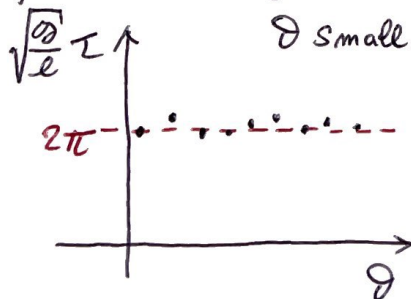
Finally, we obtain that the physical law may be recast as $\hat{F}(\Pi_1, \Pi_2) = 0 \Rightarrow \hat{F}\left(\frac{\tau^2 g}{l}, \vartheta\right) = 0$.

To further reduce the problem, assume we can INVERT (***) that is to rewrite it as:

$$\Pi_1 = G(\Pi_2) \Rightarrow \frac{\tau^2 g}{l} = G(\vartheta) \Rightarrow \tau = \sqrt{G(\vartheta)} \sqrt{\frac{l}{g}}$$

↳ just some function

To find $G(\vartheta)$ you can do EXPERIMENTS

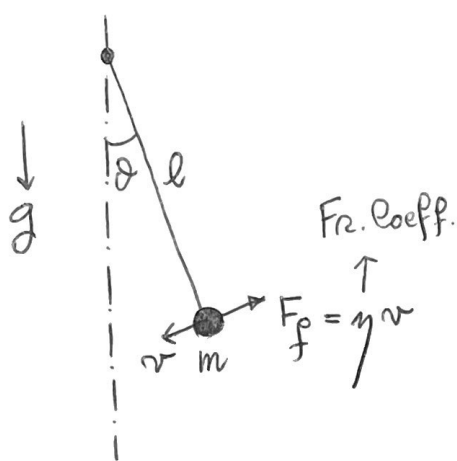


which is precisely what the theory says!

$$\tau = 2\pi \sqrt{\frac{l}{g}}$$

↳ Ps DO IT AT HOME! it's easy!

•) Simple Pendulum WITH FRICTION



With respect to the problem already seen there is a new variable:

$$\eta = \text{Friction Coefficient} = \frac{F_f}{v}$$

Dimensionally:

$$[\eta] = \frac{[F]}{[v]} = \frac{MLT^{-2}}{LT^{-1}} = MT^{-1}$$

• \$n = 6\$ since \$\{\tau, l, g, m, \theta, \eta\} = \text{involved variables}\$

• \$r = 3\$ (clearly as already seen in the prev. ex.)

\$\hookrightarrow\$ \$\Pi\$-theorem says there is a law: \$\hat{F}(\Pi_1, \Pi_2, \Pi_3) = 0\$
 \$\hookrightarrow p = n - r = 3\$.

• To find the dimless variables:

Assume: \$\Pi = \tau^a l^b g^c m^d \theta^e \eta^f\$

Impose \$[\Pi] = M^0 L^0 T^0 = \$

$$\begin{aligned} &= [\tau]^a [l]^b [g]^c [m]^d [\theta]^e [\eta]^f \\ &= T^a L^b L^c T^{-2c} M^d 1^e M^f T^{-f} \\ &= M^{(d+f)} L^{(b+c)} T^{(a-2c-f)} \end{aligned}$$

thus we get the system: (REMARK: \$e\$ drops out of the system)

$$\begin{cases} d+f=0 \\ b+c=0 \\ a-2c=f \end{cases} \quad \begin{array}{l} \text{5 unknowns in 3 equations: } \infty^2 \text{ solutions} \\ \hookrightarrow \text{WE NOW HAVE TO SELECT 2 PARAM, say} \\ \quad (e, d) \end{array}$$

THUS: \$\begin{cases} f = -d \\ b = -c \\ a = 2c + d \end{cases}\$

So \$\Pi = \tau^{2c+d} l^{-c} m^d g^c \theta^e \eta^{-d} = \left(\frac{\tau g}{l}\right)^c \left(\frac{m}{\eta \tau}\right)^d \theta^e\$

thus the 3 dimensionless v. are: \$\begin{cases} c=1, d=e=0 & \Pi_1 = \frac{\tau g}{l} \\ c=0=e, d=1 & \Pi_2 = \frac{m}{\eta \tau} \\ c=0=d, e=1 & \Pi_3 = \theta \end{cases}\$

So we have by Buckingham's theorem:

$$\hat{F}\left(\frac{\tau^2 g}{l}, \frac{m}{\eta \tau}, \theta\right) = 0$$

$\Pi_1 \quad \Pi_2 \quad \Pi_3$

WHAT IF I WANT TO FIND HOW τ DEPENDS ON THE OTHER V?

Combining dimensionless variables leads always to dimensionless variables! Let us use this fact to create a new set $(\bar{\Pi}_1, \bar{\Pi}_2, \bar{\Pi}_3)$ where τ is featured only in one variable:

$$\left. \begin{aligned} \Pi_1 &= \tau^2 \frac{g}{l} \\ \Pi_2 &= \frac{m}{\eta \tau} \end{aligned} \right\} \Rightarrow \tau = \sqrt{\frac{l}{g}} \Pi_1^{1/2} \quad \text{SET } \bar{\Pi}_1 = \Pi_1 \text{ \& } \bar{\Pi}_3 = \Pi_3$$

$$\Pi_2 = \frac{m}{\eta \tau} \Rightarrow \tau = \frac{m}{\eta \Pi_2} \Rightarrow \text{DEFINE } \bar{\Pi}_2 = \Pi_2 \Pi_1^{1/2} = \frac{m}{\eta} \sqrt{\frac{g}{l}}$$

Now: by Buckingham's theorem there will be ANOTHER

$$\bar{F}(\bar{\Pi}_1, \bar{\Pi}_2, \bar{\Pi}_3) = 0$$

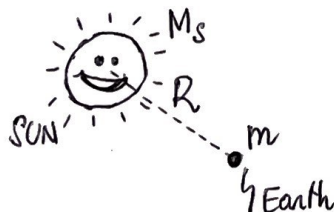
$\downarrow \quad \downarrow \quad \downarrow$
 $\tau^2 \frac{g}{l} \quad \frac{m}{\eta} \sqrt{\frac{g}{l}} \quad \theta$

So to find τ we assume \bar{F} can be inverted:

$$\bar{\Pi}_1 = \mathcal{G}(\bar{\Pi}_2, \bar{\Pi}_3) \Rightarrow \tau = \sqrt{\frac{l}{g}} \sqrt{\mathcal{G}\left(\frac{m}{\eta} \sqrt{\frac{g}{l}}, \theta\right)}$$

Correction due to initial amplitude & air viscosity

● KEPLER'S LAW - find the period of revolution of the Earth around the Sun



$m \ll M$ we can neglect it

Variables: $(\tau, M, R, \mathcal{G})$ $n = 4$

\mathcal{G} = universal constant of gravitation

\mathcal{L} [\mathcal{G}] given by Newton's law:

$$F = \mathcal{G} \cdot \frac{m_1 m_2}{r^2} \Rightarrow [\mathcal{G}] = [F][r]^2 [m_1]^{-1} [m_2]^{-1}$$

$$[\mathcal{G}] = \text{MLT}^{-2} \cdot \text{L}^2 \cdot \text{M}^{-1} \text{M}^{-1} = \text{M}^{-1} \text{L}^3 \text{T}^{-2}$$

$$\left\{ \begin{array}{l} [\tau] = T \\ [M] = M \\ [R] = L \\ [G] = M^{-1} L^3 T^{-2} \end{array} \right. \Rightarrow r = 3 \text{ (3 fund. units define all vars.)}$$

THERE IS ONLY $1 = n - r = 4 - 3$ DIMENSIONLESS Π .

to find it:

$$\Pi = M^a R^b \tau^c G^d \Rightarrow \text{impose } [\Pi] = M^0 L^0 T^0$$

$$[\Pi] = M^a L^b (T^c) (M^{-1} L^3 T^{-2})^d = M^{(a-d)} L^{(b+3d)} T^{(c-2d)}$$

we get the system:

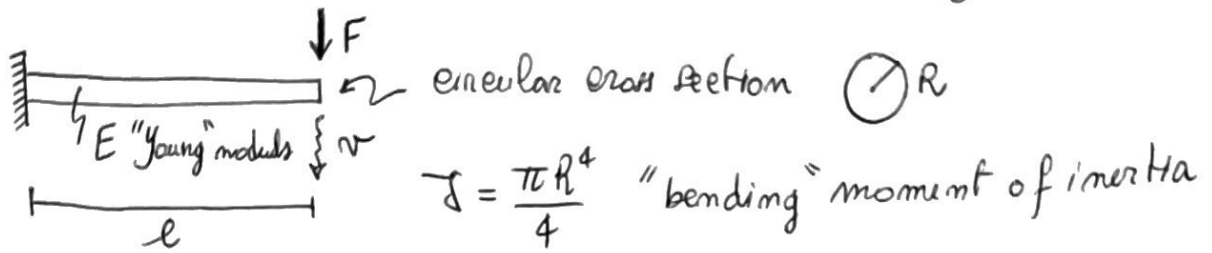
$$\left\{ \begin{array}{l} a - d = 0 \\ b + 3d = 0 \\ c - 2d = 0 \end{array} \right. \begin{array}{l} 4 \text{ unknowns} \\ \times \\ 3 \text{ equations} \end{array} \Rightarrow \infty^1 \text{ solutions - take } \underline{d} \text{ as param.}$$

$$\left\{ \begin{array}{l} a = d \\ b = -3d \\ c = 2d \end{array} \right. \quad \Pi = \left(\frac{M \tau^2 G}{R^3} \right)^d \quad \text{set } d=1 \quad \Pi = \frac{M \tau^2 G}{R^3}$$

we obtain that $\tau^2 = \frac{\Pi}{M G} R^3 \Rightarrow$ THE SQUARE OF THE PERIOD IS PROPORTIONAL TO THE CUBE OF THE DISTANCE.

Exceptional Cases: WHEN $r \neq 3$!

- Cantilever Problem: find the displacement $v \approx \frac{Fl^3}{EJ}$



- $n = 5$ since involved variables are (v, F, l, E, J)

• $r = ?$ $[F] = MLT^{-2} \rightarrow$ SET $X = MT^{-2} \rightarrow [F] = XL$
 $[v] = L$
 $[E] = [\text{force}]/[\text{area}] = \frac{MLT^{-2}}{L^2} = ML^{-1}T^{-2} \rightarrow [E] = XL^{-1}$
 $[l] = L$
 $[J] = L^4$

thus we see that only A COMBINATION of MLT , $X = MT^{-2}$, plays a role $\Rightarrow r = 2 \Rightarrow$ there are $p = n - r = 5 - 2 = 3$ DIM. LESS V.

- to find the Π , assume $\Pi = F^a v^b E^c l^d J^e$ thus

$$[\Pi] = [F^a v^b E^c l^d J^e] = (XL)^a L^b (XL^{-1})^c L^d L^{4e} = X^{(a+c)} L^{(a+b-c+d+4e)} = X^0 L^0$$

so we get the system of 2 EQUATIONS for 5 UNKNOWN

$$\begin{cases} a+c=0 \\ a+b-c+d+4e=0 \end{cases} \quad 5-2=3 \Rightarrow \infty^3 \text{ solutions} \Rightarrow \text{SET } \frac{1}{3} \text{ PARAMETERS: say } b, c, e$$

then

$$\begin{cases} a = -c \\ d = 2c - b - 4e \end{cases} \Rightarrow \Pi = F^{-c} v^b E^c l^{2c-b-4e} J^e = \left(\frac{El^2}{F}\right)^c \left(\frac{v}{l}\right)^b \left(\frac{J}{l^4}\right)^e$$

thus by Buckingham's theorem we get: $\begin{cases} \Pi_1 = \frac{El^2}{F} \\ \Pi_2 = v/l \\ \Pi_3 = J/l^4 \end{cases}$

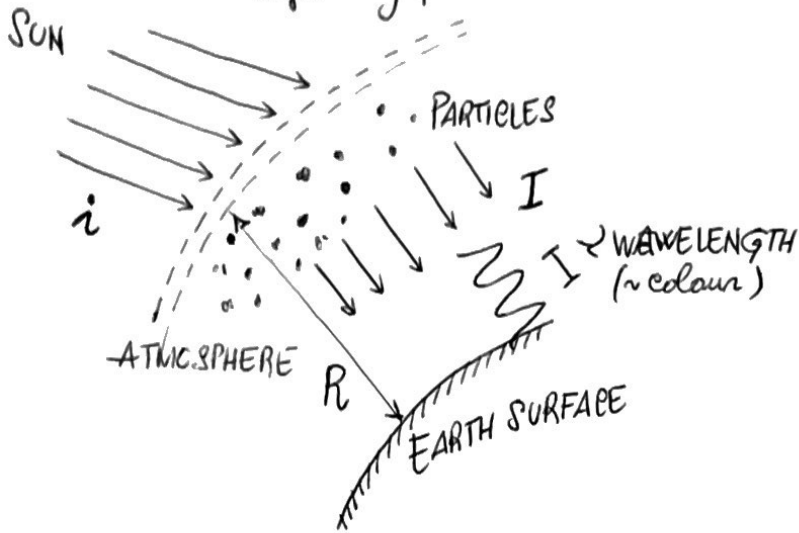
$$\hat{F}\left(\frac{El^2}{F}, \frac{v}{l}, \frac{J}{l^4}\right) = 0 \Rightarrow \frac{v}{l} = G\left(\frac{El^2}{F}, \frac{J}{l^4}\right).$$

In fact if we take a simple expression: $\frac{v}{l} = \frac{F}{El^2} \cdot \frac{J}{l^4} \Rightarrow v \approx \frac{Fl^3}{EJ}$

Give for home: Scattering problem (similar to the previous)

- WHY IS THE SKY BLUE? (Also this is a case where $r=2$!)

The apparent colour of the sky is due to scattering of sunlight by particles in the atmosphere of the Earth



I = intensity of light after scattering
 i = intensity of light before scattering
 λ = wavelength
 V = volume of particles
 R = distance from the earth's crust.

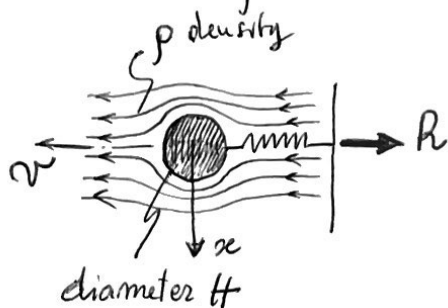
Find how λ depends on the involved variables.

$$P.S \quad [i] = [I] = [\text{energy}] [\text{area}]^{-1} [\text{time}]^{-1}$$

$$[\lambda] = L$$

As in the previous problem you will find that $r=2$!

- Problem of motion in a viscous fluid (Reynolds number)



"dynamic viscosity" relates:

$$\frac{R}{A} = \frac{\mu}{\frac{dv}{dx}}$$

force on the object divided by area A μ gradient of velocity

dynamic viscosity

Find a ^{dimensionless} relation among (R, μ, ρ, H, v) $n=5$

Buckingham's theorem says:

$$F(R, \mu, \rho, H, v) = 0 \Leftrightarrow \hat{F}(\Pi_1, \Pi_2, \dots, \Pi_p) = 0$$

$$L_p = n - r$$

• Find v :

$$\rho \left[\mu \right] = \frac{[R/A]}{[v/L]} = \frac{MLT^{-2} \cdot L^{-1}}{LT^{-1} \cdot L^{-1}} = ML^{-1}T^{-1}$$

$$[R] = MLT^{-2}$$

$$[H] = L$$

$$[\rho] = ML^{-3}$$

$$[v] = LT^{-1}$$

thus $r=3 \Rightarrow p=n-r=5-3=2$

there are 2 dimensionless v .

• Find Π s: $\Pi = R^a H^b \rho^c \mu^d v^e$

$$\begin{aligned} [\Pi] &= M^0 L^0 T^0 = [R]^a [H]^b [\rho]^c [\mu]^d [v]^e = \dots \\ &= M^{(a+c+d)} L^{(a+b-3c-d+e)} T^{(-2a-d-e)} \end{aligned}$$

hence the system:

$$\begin{cases} a+c+d=0 \\ a+b-3c-d+e=0 \\ -2a-d-e=0 \end{cases}$$

5 unknowns \times 3 equations
 $L^{\otimes 2}$ solutions \Rightarrow set 2 parameters
 (a, d)

$$\dots \begin{cases} b = -2a-d \\ e = -a-d \\ e = -2a-d \end{cases} \Rightarrow \Pi = \left(\frac{R}{H^2 \rho v^2} \right)^a \left(\frac{H}{H \rho v} \right)^d$$

$$\text{thus } \Pi_1 = \frac{R}{H^2 \rho v^2}; \Pi_2 = \frac{H}{H \rho v}$$

"Drag Coefficient"

"Reynolds number"

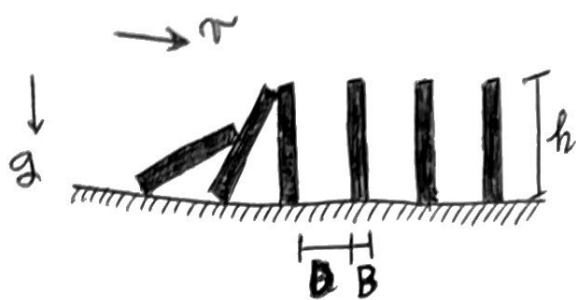
(actually the inverse: $Re = \frac{H \rho v}{\mu}$)

So $\hat{F}(\Pi_1, \Pi_2) = 0$ by imposing invertibility:

$$\Pi_1 = G(\Pi_2) \Rightarrow \frac{R}{H^2 \rho v^2} = G\left(\frac{H}{H \rho v}\right)$$

it defines the transition between LAMINAR & TURBULENT flow.

•) Toppling Dominoes Problem:



Find how velocity v depends on the remaining variables

$$F(v, D, B, h, g) = 0 \quad n=5$$

• find v ?

$$\begin{cases} [v] = LT^{-1} \\ [g] = LT^{-2} \\ [D] = [h] = [B] = L \end{cases}$$

• Construct dimensionless variables:

$$\Pi = v^a D^b B^c h^d g^e \Rightarrow \text{impose } [\Pi] = M^0 L^0 T^0$$

$$\text{thus } [\Pi] = \dots = L^{(a+b+c+d+e)} T^{(-a-2e)}$$

$$\text{thus } \begin{cases} a+b+c+d+e=0 & \text{5 unknowns} \times 2 \text{ eqns} \\ a+2e=0 & \end{cases} \quad p = n - r = 3 \text{ dimless variables}$$

• thus $\Pi = v^{(-2e)} D^{(e-c-d)} B^e h^d g^e =$

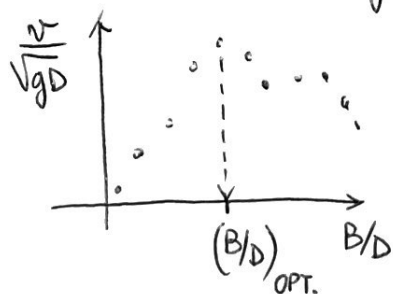
$$= \left(\frac{B}{D} \right)^c \left(\frac{h}{D} \right)^d \left(\frac{gD}{v^2} \right)^e$$

$$\begin{matrix} \Pi_1 & \Pi_2 & \Pi_3 \end{matrix}$$

$$\hat{F}(\Pi_1, \Pi_2, \Pi_3) = 0 \Rightarrow \Pi_3 = G(\Pi_1, \Pi_2) \Rightarrow v = \sqrt{gD} \hat{G}\left(\frac{B}{D}, \frac{h}{D}\right)$$

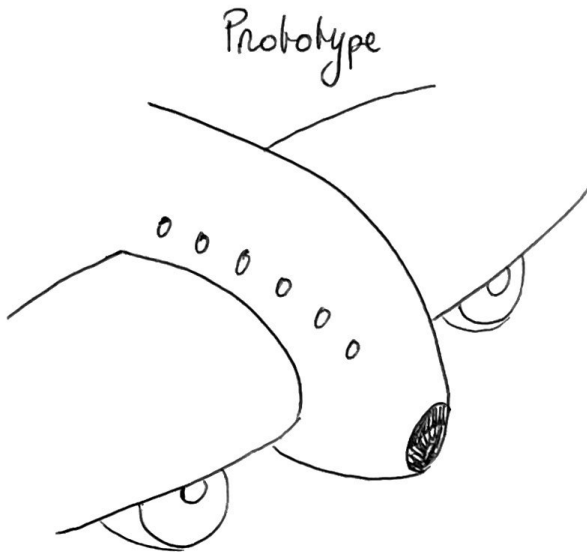
• Experiments may be carried to find for example how does the distance B play an influence on v ?

Neglect h/D & plot v/\sqrt{gD} vs B/D



■ PHYSICAL SIMILARITY

Consider a PROTOTYPE of an airplane and its MODEL

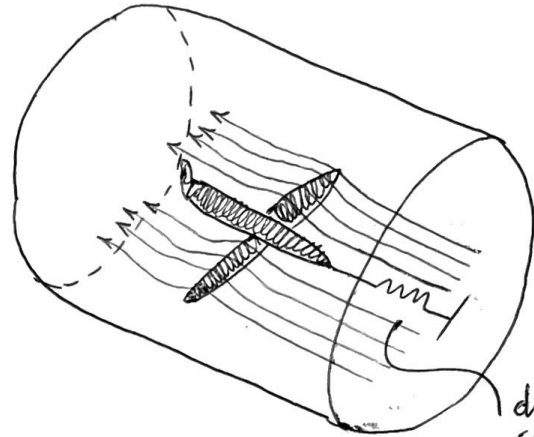


involved variables:
 $(\rho^P, \mu^P, F^P, H^P, v^P)$

↓
 Buckingham Th
 (see p. 8)

$$\Pi_1^P = G^P(\Pi_2^P) \quad \left\{ \begin{array}{l} \Pi_1^P = \frac{F^P}{H_P^2 \rho_P v_P^2} \\ \Pi_2^P = \frac{\mu^P}{H_P \rho_P v_P} \end{array} \right.$$

Model in wind tunnel



involved variables
 $(\rho^M, \mu^M, F^M, H^M, v^M)$

↓
 Buckingham's th

$$\Pi_1^M = G^M(\Pi_2^M) \quad \left\{ \begin{array}{l} \Pi_1^M = \frac{F^M}{\rho_M v_M^2 H_M^2} \\ \Pi_2^M = \frac{\mu_M}{H_M \rho_M v_M} \end{array} \right.$$

dynamometer to measure the drag force

- Physical similarity exploits the fact that a physical phenomenon only depends on dimensionless variables; hence the effects taking place in the prototype and in the model are the same if

$$\left\{ \begin{array}{l} G^P = G^M \\ \Pi_1^P = \Pi_1^M \\ \Pi_2^P = \Pi_2^M \\ \vdots \end{array} \right.$$

(until you saturate all the list of variables)

-) Example: A prototype of an airplane runs at $v_p = 800 \text{ km/h}$ in air (density ρ , dynamic viscosity μ). The engines exert a force F_p , completely balanced by air resistance in stationary conditions. Its size (length) is H_p . A model of the same airplane is designed to fulfill physical similarity, it has length $H_M = \frac{1}{10} H_p$, it runs in air with same values as in the prototype. A force $F_M = 15 \text{ kN}$ is measured on the model in a wind tunnel.
- 1) Find the velocity v_M of the model that secures physical similarity.
 - 2) What is the value of F_p ?

Solution: to ensure physical similarity impose:

$$\cdot \Pi_1^P = \Pi_1^M \Rightarrow \frac{F^P}{\rho v_p^2 H_p^2} = \frac{F_M}{\rho v_M^2 H_M^2} \Rightarrow F_p = F_M \cdot \left(\frac{v_p}{v_M}\right)^2 \left(\frac{H_p}{H_M}\right)^2 \quad (*)$$

$$\cdot \Pi_2^P = \Pi_2^M \Rightarrow \frac{\mu}{\rho v_p H_p} = \frac{\mu}{\rho v_M H_M} \Rightarrow v_M = v_p \left(\frac{H_p}{H_M}\right) = \underset{800}{800} \underset{10}{10} = 8000 \text{ km/h} \checkmark$$

Thus from (*) we get:

$$F_p = F_M \cdot \left(\frac{v_p}{v_M}\right)^2 \cdot \left(\frac{H_p}{H_M}\right)^2 = F_M = 15 \text{ kN}.$$

— End of Dimensional Analysis —

(EHM... a bit too much!)
but ok it's only for theoret. purposes.
Actually, the highest velocity in a wind tunnel is about 650 km/h
So - if you want to reproduce the same physical effects with lower velocities, you need to change density & viscosity