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Dr. Class Röven - Assignment 2 Solutions

1. If $R(t) = (x(t), y(t))$, then $R'(t) = (x'(t), y'(t))$

$$a) R(t) = (\sin(t), \cos(3t)), \quad t \in [0, \pi]$$

$$R'(t) = (\cos(t), -3\sin(3t))$$

to sketch the curve, we find the endpoints

$$R(0) = (\sin(0), \cos(0)) = (0, 1)$$

$$R(\pi) = (\sin(\pi), \cos(3\pi)) = (0, -1)$$

and notice that if $t \in (0, \pi)$ then $\sin(t) > 0$.

now, we find that $\cos(3t) = 0 \Leftrightarrow t = \frac{m\pi}{3} + \frac{\pi}{6}$,
 $m \in \mathbb{Z}$. only $m = 0, 1, 2$ give t values in the domain
of $R(t)$.

$$m = 0 \Rightarrow t = \frac{\pi}{6} \quad \text{gives } (\sin(\frac{\pi}{6}), 0) = (\frac{1}{2}, 0)$$

$$m = 1 \Rightarrow t = \frac{\pi}{2} \quad \text{gives } (\sin(\frac{\pi}{2}), 0) = (1, 0)$$

$$m = 2 \Rightarrow t = \frac{5\pi}{6} \quad \text{gives } (\sin(\frac{5\pi}{6}), 0) = (\frac{1}{2}, 0)$$

also, we find that $\cos(3t) = 1 \Leftrightarrow t = \frac{m2\pi}{3}$, $m \in \mathbb{Z}$

and $\cos(3t) = -1 \Leftrightarrow t = \frac{(2m+1)\pi}{3}$, $m \in \mathbb{Z}$. the

only solutions in the domain of $R(t)$ are

$$\cos(3t) = 1 \Rightarrow t = \frac{2\pi}{3} \quad \text{gives } (\sin(\frac{2\pi}{3}), 1) = (\frac{\sqrt{3}}{2}, 1)$$

$$\cos(3t) = -1 \Rightarrow t = \frac{\pi}{3} \quad \text{gives } (\sin(\frac{\pi}{3}), -1) = (\frac{\sqrt{3}}{2}, -1)$$

now using that

$$3t \in (0, \frac{\pi}{2}) \Rightarrow \cos(3t) > 0$$

$$3t \in (\frac{\pi}{2}, \frac{3\pi}{2}) \Rightarrow \cos(3t) < 0$$

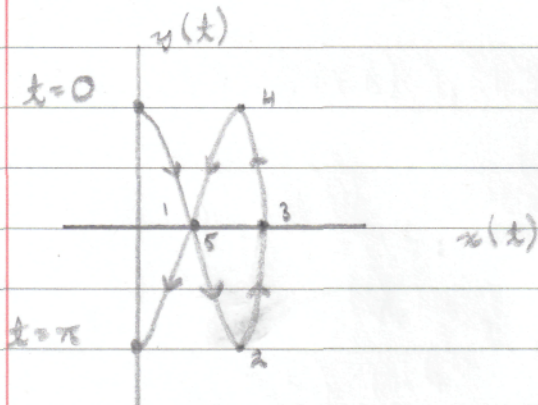
$$3t \in (\frac{3\pi}{2}, 2\pi) \Rightarrow \cos(3t) > 0$$

we sketch $R(t)$

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reflective symmetry in
 $x(t)$ axis.

$$1 - t = \frac{\pi}{6}, \quad 4 - t = \frac{2\pi}{3}$$

$$2 - t = \frac{\pi}{3}, \quad 5 - t = \frac{5\pi}{6}$$

$$3 - t = \frac{\pi}{2}$$

$$b) \quad \mathbf{r}(t) = ((1-t^2)\cos(4\pi t), (1-t^2)\sin(4\pi t), t), \quad t \in [-1, 1]$$

$$\mathbf{r}'(t) = (-4\pi(1-t^2)\sin(4\pi t) - 2t\cos(4\pi t),$$

$$4\pi(1-t^2)\cos(4\pi t) - 2t\sin(4\pi t),$$

$$1)$$

to sketch the curve, we consider the 2D projection
 $\bar{\mathbf{r}}(t) = ((1-t^2)\cos(4\pi t), (1-t^2)\sin(4\pi t))$ of $\mathbf{r}(t)$

notice that $(1-t^2) \geq 0$ on the domain of $\mathbf{r}(t)$ and
 $1-t^2 = 0 \Rightarrow t = \pm 1$

thus, both endpoints of $\bar{\mathbf{r}}(t)$ are $(0, 0)$

$\bar{\mathbf{r}}(t)$ intercepts the x -axis when $\sin(4\pi t) = 0$
 $\Rightarrow 4\pi t = m\pi$ where $m \in \mathbb{Z}$
 $t = \frac{m}{4}$

thus we get new x intercepts when
 $t = -3/4, -1/2, -1/4, 0, 1/4, 1/2, 3/4$

this gives the points (respectively)

- also, $\bar{z}(t)$ intersects the y -axis when $\cos(4\pi t) = 0$
 $\Rightarrow 4\pi t = m\pi + \frac{\pi}{2}$ where $m \in \mathbb{Z}$
 $t = \frac{m}{4} + \frac{1}{8}$
- $t < 0$
 - $(-\frac{7}{16}, 0)$
 - $(-\frac{3}{4}, 0)$
 - $(-\frac{5}{16}, 0)$
 - $(1, 0)$
 - $t = 0$
 - $(-\frac{5}{16}, 0)$
 - $(\frac{3}{4}, 0)$
 - $t > 0$
 - $(-\frac{1}{16}, 0)$
 - $(\frac{3}{4}, 0)$
 - $(\frac{7}{16}, 0)$

thus we get y intercepts where $t = -\frac{7}{8}, -\frac{5}{8}, -\frac{3}{8}, -\frac{1}{8}, \frac{1}{8}, \frac{3}{8}, \frac{5}{8}, \frac{7}{8}$

this gives the points (respectively)

- $t < 0$
 - $(0, \frac{15}{64})$
 - $(0, -\frac{39}{64})$
 - $(0, \frac{55}{64})$
 - $(0, -\frac{63}{64})$
- $t = 0$
 - $(0, \frac{63}{64})$
 - $(0, -\frac{55}{64})$
 - $(0, \frac{39}{64})$
 - $(0, -\frac{15}{64})$

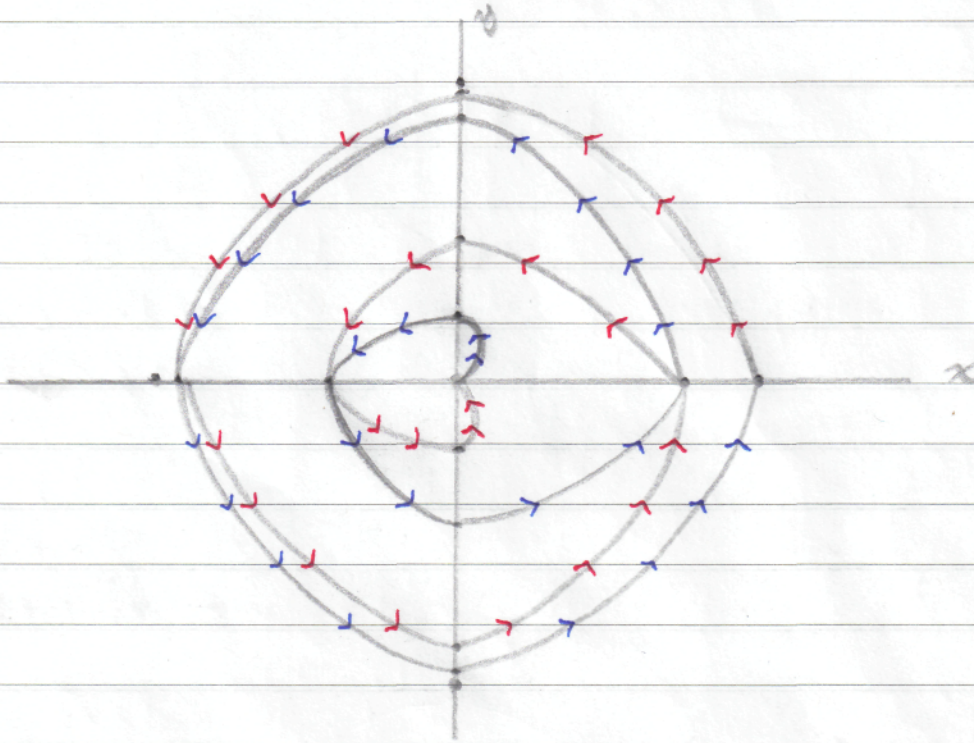
now, since $4\pi t$ increases as t increases, positive orientation is anticlockwise.

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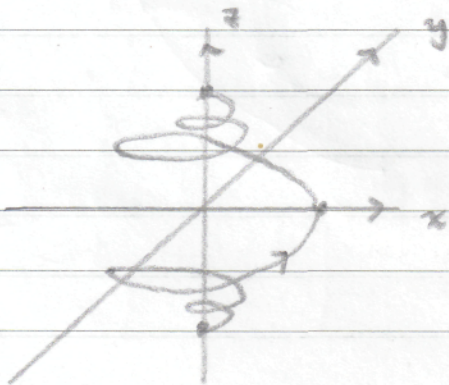
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using blue for negative values of t and red for positive values of t , we find the graph of $\bar{R}(t)$ is approximately



this sketch of $\bar{R}(t)$ allows better visualization of $R(t)$ which thus resembles



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$$2. P = (1/\sqrt{2}, 1/2, 1/2), Q = (-1/\sqrt{2}, 1/2, -1/2)$$

$$\begin{aligned} a) \ell(t) &= \left(\frac{(1-t)}{\sqrt{2}} - \frac{t}{\sqrt{2}}, \frac{(1-t)}{2} + \frac{t}{2}, \frac{(1-t)}{2} - \frac{t}{2} \right) \\ &= \left(\frac{(1-2t)}{\sqrt{2}}, \frac{1}{2}, \frac{(1-2t)}{2} \right) \end{aligned}$$

$t \in [0, 1]$ is a parametrization of the line segment from P to Q .

b) the straight-line distance between 2 points $A = (a_1, a_2, a_3)$ and $B = (b_1, b_2, b_3)$ in \mathbb{R}^3 is given by

$$|AB| = \sqrt{(a_1 - b_1)^2 + (a_2 - b_2)^2 + (a_3 - b_3)^2}$$

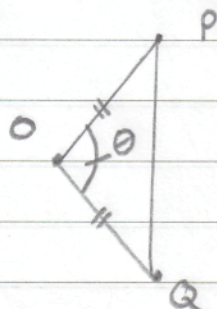
a point is on the unit sphere S if it is distance 1 from the origin $O = (0, 0, 0)$

$$|OP| = \sqrt{1/2 + 1/4 + 1/4} = 1$$

$$|OQ| = \sqrt{1/2 + 1/4 + 1/4} = 1$$

so P and Q are on the unit sphere.

the vectors P and Q define a plane. in this plane we have the triangle



to solve for θ , we first need the straight-line distance from P to Q

$$|PQ| = \sqrt{(2/\sqrt{2})^2 + 1} = \sqrt{3}$$

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now, we may solve for θ using the cosine rule

$$(\sqrt{3})^2 = 1^2 + 1^2 - 2(1)(1)\cos\theta$$

$$-1 = 2\cos\theta$$

$$\cos\theta = -\frac{1}{2}$$

$$\Rightarrow \theta = \frac{2\pi}{3}$$

the "equator" of the unit sphere S is parametrised by $(\cos(t), \sin(t), 0)$ where $t \in [0, 2\pi)$

we map the "equator" to the great circle through P and Q by finding a 3×3 matrix that maps $(\cos(0), \sin(0), 0) = (1, 0, 0)$ to P and maps $(\cos(\theta), \sin(\theta), 0) = (-\frac{1}{2}, \frac{\sqrt{3}}{2}, 0)$ to Q

now we have

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix}$$

by the rules of matrix multiplication,

$$a(1) = \frac{1}{\sqrt{2}}$$

$$d(1) = \frac{1}{2}$$

$$g(1) = \frac{1}{2}$$

$$\text{then } \begin{pmatrix} \frac{1}{\sqrt{2}} & b & c \\ \frac{1}{2} & e & f \\ \frac{1}{2} & h & i \end{pmatrix} \begin{pmatrix} -\frac{1}{2} \\ \frac{\sqrt{3}}{2} \\ 0 \end{pmatrix} = \begin{pmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{2} \\ -\frac{1}{2} \end{pmatrix}$$

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allow us to solve for b , e , h as

$$\left(\frac{1}{\sqrt{2}}\right)\left(-\frac{1}{2}\right) + b\left(\frac{\sqrt{3}}{2}\right) = -\frac{1}{\sqrt{2}}$$

$$b\left(\frac{\sqrt{3}}{2}\right) = \frac{1}{2\sqrt{2}} - \frac{1}{\sqrt{2}} = -\frac{1}{2\sqrt{2}}$$

$$b = -\frac{1}{2\sqrt{2}}\left(\frac{2}{\sqrt{3}}\right) = -\frac{1}{\sqrt{6}}$$

$$\left(\frac{1}{2}\right)\left(-\frac{1}{2}\right) + e\left(\frac{\sqrt{3}}{2}\right) = \frac{1}{2}$$

$$e\left(\frac{\sqrt{3}}{2}\right) = \frac{1}{2} + \frac{1}{4} = \frac{3}{4}$$

$$e = \frac{3}{4}\left(\frac{2}{\sqrt{3}}\right) = \frac{3}{2\sqrt{3}} = \frac{\sqrt{3}}{2}$$

$$\left(\frac{1}{2}\right)\left(-\frac{1}{2}\right) + h\left(\frac{\sqrt{3}}{2}\right) = -\frac{1}{2}$$

$$h\left(\frac{\sqrt{3}}{2}\right) = -\frac{1}{2} + \frac{1}{4} = -\frac{1}{4}$$

$$h = -\frac{1}{4}\left(\frac{2}{\sqrt{3}}\right) = -\frac{1}{2\sqrt{3}}$$

now we map the equator to the great circle through P and Q by

$$\begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} & 2 \\ \frac{1}{2} & \frac{\sqrt{3}}{2} & t \\ \frac{1}{2} & -\frac{1}{2\sqrt{3}} & i \end{pmatrix} \begin{pmatrix} \cos(t) \\ \sin(t) \\ 0 \end{pmatrix}$$

notice that changing the values of e , f and i will have no effect

thus a parametrization for the great circle through P and Q is given by

$$\begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{\sqrt{2}} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} \cos(t) \\ \sin(t) \\ 0 \end{pmatrix} + \begin{pmatrix} -\frac{1}{\sqrt{6}} & \frac{\sqrt{3}}{2} & -\frac{1}{2\sqrt{3}} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2\sqrt{3}} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} \cos(t) \\ \sin(t) \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{\cos(t)}{\sqrt{2}} - \frac{\sin(t)}{\sqrt{6}} & \frac{\cos(t)}{2} + \frac{\sqrt{3}\sin(t)}{2} & \frac{\cos(t)}{2} - \frac{\sin(t)}{2\sqrt{3}} \end{pmatrix}$$

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where $t \in [0, 2\pi)$. we use the parametrisation to the parametrisation of the short arc from P to Q using the same parametrisation but with $t \in [0, 2\pi/3]$.

a) the length of the line segment from P to Q is the straight-line distance from P to Q , worked out previously.

$$|PQ| = \sqrt{3}$$

the length of the the short arc of the great circle from P to Q depends only on the angle $\Theta = 2\pi/3$ worked out earlier.

the arc length is $2\pi \left(\frac{2\pi/3}{2\pi} \right) = 2\pi/3$.

NOTE: b) can be solved by

$g(t) = \cos(t)P + \sin(t)Q_p$ where Q_p is found by

$$w = Q - \left(\frac{P \cdot Q}{P \cdot P} \right) P$$

and

$$Q_p = \frac{w}{\|w\|}.$$

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3. Let $r(t)$ be a parametric curve and $t = t(s)$ be a reparametrization.

Suppose $r(t) = (x_1(t), \dots, x_n(t))$. Now,

$$\frac{dr}{dt} = \left(\frac{dx_1}{dt}, \dots, \frac{dx_n}{dt} \right)$$

If $t = t(s)$ is a reparametrization,

$$r(t(s)) = (x_1(t(s)), \dots, x_n(t(s))) \quad \text{and}$$

$$\frac{dr}{ds} = \left(\frac{dx_1}{dt} \frac{dt}{ds}, \dots, \frac{dx_n}{dt} \frac{dt}{ds} \right)$$

$$= \frac{dt}{ds} \left(\frac{dx_1}{dt}, \dots, \frac{dx_n}{dt} \right)$$

$$= \frac{dt}{ds} \frac{dr}{dt} \quad \text{by the chain rule.}$$

$\frac{dt}{ds}$ is a scalar and so $\frac{dr}{ds}$ is a scalar multiple of $\frac{dr}{dt}$. This implies that $\frac{dr}{ds}$ and $\frac{dr}{dt}$ are parallel vectors.

$$\left\| \frac{dr}{dt} \right\| = \left(\left(\frac{dx_1}{dt} \right)^2 + \dots + \left(\frac{dx_n}{dt} \right)^2 \right)^{1/2} \quad \text{and}$$

$$\left\| \frac{dr}{ds} \right\| = \left(\left(\frac{ds}{dt} \right)^2 \left(\left(\frac{dx_1}{dt} \right)^2 + \dots + \left(\frac{dx_n}{dt} \right)^2 \right) \right)^{1/2}$$

$$= \left| \frac{ds}{dt} \right| \left\| \frac{dr}{dt} \right\|$$

thus the length of $\frac{dr}{ds}$ is the length of $\frac{dr}{dt}$ multiplied by the absolute value of $\frac{ds}{dt}$.

$\frac{dr}{dt}$ is called velocity and $\left\| \frac{dr}{dt} \right\|$ is called speed.

4. If $r: \mathbb{R} \rightarrow \mathbb{R}^3$ is a parametrization, the curvature function $\kappa(t)$ of $r(t)$ is given by

$$\kappa(t) = \frac{\|r''(t) \times r'(t)\|}{\|r'(t)\|^3}$$

a) $r(t) = (t^2, \sin(t) - t \cos(t), \cos(t) + t \sin(t))$

$$r'(t) = (2t, t \sin(t), t \cos(t))$$

$$r''(t) = (2, \sin(t) + t \cos(t), \cos(t) - t \sin(t))$$

$$r''(t) \times r'(t) = \begin{vmatrix} i & j & k \\ 2 & \sin(t) + t \cos(t) & \cos(t) - t \sin(t) \\ 2t & t \sin(t) & t \cos(t) \end{vmatrix}$$

$$= i (t \cos(t) (\sin(t) + t \cos(t)) - t \sin(t) (\cos(t) - t \sin(t)))$$

$$- j (2t \cos(t) - 2t (\cos(t) - t \sin(t)))$$

$$+ k (2t \sin(t) - 2t (\sin(t) + t \cos(t)))$$

$$= i (t \cos(t) \sin(t) + t^2 \cos^2(t) - t \sin(t) \cos(t) + t^2 \sin^2(t))$$

$$- j (2t^2 \sin(t)) + k (-2t^2 \cos(t))$$

$$= i (t^2 (\cos^2(t) + \sin^2(t))) + j (-2t^2 \sin(t)) + k (-2t^2 \cos(t))$$

$$= (t^2, -2t^2 \sin(t), -2t^2 \cos(t))$$

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$$\begin{aligned}\|r'(t)\| &= \left(4t^2 + t^2 \sin^2(t) + t^2 \cos^2(t)\right)^{1/2} \\ &= \left(4t^2 + t^2(\cos^2(t) + \sin^2(t))\right)^{1/2} \\ &= \left(5t^2\right)^{1/2} = \sqrt{5}|t|\end{aligned}$$

$$\begin{aligned}\|r''(t) \times r'(t)\| &= \left(t^4 + 4t^4 \sin^2(t) + 4t^4 \cos^2(t)\right)^{1/2} \\ &= \left(t^4 + 4t^4(\cos^2(t) + \sin^2(t))\right)^{1/2} \\ &= \left(5t^4\right)^{1/2} = \sqrt{5}t^2\end{aligned}$$

so

$$K(t) = \frac{\sqrt{5}t^2}{(\sqrt{5}|t|)^3} = \frac{\sqrt{5}t^2}{5\sqrt{5}|t|^3} = \frac{1}{5|t|}$$

$$b) r(t) = (t^2, 2t, \ln(t))$$

$$r'(t) = (2t, 2, 1/t)$$

$$r''(t) = (2, 0, -1/t^2)$$

$$r''(t) \times r'(t) = \begin{vmatrix} i & j & k \\ 2 & 0 & -1/t^2 \\ 2t & 2 & 1/t \end{vmatrix}$$

$$= i\left(\frac{2}{t^2}\right) - j\left(\frac{2}{t} + \frac{2t}{t^2}\right) + k(4)$$

$$= \left(\frac{2}{t^2}, -\frac{4}{t}, 4\right)$$

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$$\|r'(t)\| = (4t^2 + 4 + 1/t^2)^{1/2}$$

$$= \sqrt{\frac{4t^4 + 4t^2 + 1}{t^2}} = \frac{(4t^4 + 4t^2 + 1)^{1/2}}{|t|}$$

$$\|r''(t) \times r'(t)\| = (4/t^4 + 16/t^2 + 16)^{3/2}$$

$$= \sqrt{\frac{4(4t^4 + 4t^2 + 1)}{t^4}} = \frac{2(4t^4 + 4t^2 + 1)^{1/2}}{t^2}$$

so

$$K(t) = \left(\frac{2(4t^4 + 4t^2 + 1)^{1/2}}{t^2} \right) \left(\frac{|t|^3}{(4t^4 + 4t^2 + 1)^{3/2}} \right)$$

$$= \frac{2|t|}{4t^4 + 4t^2 + 1}$$

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$$5. \quad r(t) = (2 \sin(3t), t, 2 \cos(3t))$$

$$r(t) = (0, \pi, -2) \text{ when } t = \pi$$

the osculating plane of $r(t)$ is defined by the unit tangent vector

$$T(t) = \frac{r'(t)}{\|r'(t)\|}$$

and the unit normal vector

$$N(t) = \frac{T'(t)}{\|T'(t)\|}$$

$$r'(t) = (6 \cos(3t), 1, -6 \sin(3t))$$

$$\begin{aligned} \|r'(t)\| &= (1 + 36 \cos^2(3t) + 36 \sin^2(3t))^{1/2} \\ &= \sqrt{37} \end{aligned}$$

$$\text{so } T(t) = \frac{1}{\sqrt{37}} (6 \cos(3t), 1, -6 \sin(3t))$$

$$T'(t) = \frac{1}{\sqrt{37}} (-18 \sin(3t), 0, -18 \cos(3t))$$

$$\begin{aligned} \|T'(t)\| &= \left(\frac{18^2}{37} \sin^2(3t) + \frac{18^2}{37} \cos^2(3t) \right)^{1/2} \\ &= \frac{18}{\sqrt{37}} \end{aligned}$$

$$\text{so } N(t) = \frac{\sqrt{37}}{18} \left(\frac{1}{\sqrt{37}} (-18 \sin(3t), 0, -18 \cos(3t)) \right)$$

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$$= (-\sin(3t), 0, -\cos(3t))$$

a vector normal to this plane is given by the binormal vector

$$B(t) = T(t) \times N(t)$$

at $t = \pi$ we have

$$B(\pi) = T(\pi) \times N(\pi)$$

$$= \frac{1}{\sqrt{37}} (6 \cos(3\pi), 1, -6 \sin(3\pi)) \times (-\sin(3\pi), 0, -\cos(3\pi))$$

$$= \frac{1}{\sqrt{37}} (-6, 1, 0) \times (0, 0, 1)$$

$$= \begin{vmatrix} i & j & k \\ -6/\sqrt{37} & 1/\sqrt{37} & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

$$= i \left(\frac{1}{\sqrt{37}} \right) - j \left(-\frac{6}{\sqrt{37}} \right) + k(0)$$

$$= \frac{i}{\sqrt{37}} + \frac{6j}{\sqrt{37}} + 0k$$

$$= \left(\frac{1}{\sqrt{37}}, \frac{6}{\sqrt{37}}, 0 \right)$$

since $B(\pi)$ is normal to the osculating plane, $\sqrt{37} B(\pi) = (1, 6, 0)$ is normal also.

now, the osculating plane is defined by $1(x-0) + 6(y-\pi) + 0(z-2) = 0$

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this gives the plane $x + by = b\pi$.

to find the osculating circle, we must find the curvature

$$\kappa(t) = \frac{\|r''(t) \times r'(t)\|}{\|r'(t)\|^3}$$

$$\|r'(t)\| = \sqrt{37}$$

$$r''(t) = (-18 \sin(3t), 0, -18 \cos(3t))$$

$$r''(t) \times r'(t) = \begin{vmatrix} i & j & k \\ -18 \sin(3t) & 0 & -18 \cos(3t) \\ 6 \cos(3t) & 1 & -6 \sin(3t) \end{vmatrix}$$

$$= i(18 \cos(3t)) - j(108 \sin^2(3t) + 108 \cos^2(3t)) + k(-18 \sin(3t))$$

$$= (18 \cos(3t), -108, -18 \sin(3t))$$

$$\|r''(t) \times r'(t)\| = \sqrt{19^2 + 108^2} = \sqrt{11988} = 18\sqrt{37}$$

$$\kappa(t) = \frac{18\sqrt{37}}{37\sqrt{37}} = \frac{18}{37}$$

and the radius of the osculating circle is

$$R(t) = \frac{37}{18}$$

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the unit normal vector to $\kappa(t)$ at $(0, \pi, -2)$ is $N(\pi) = (0, 0, 1)$ which points to the centre of the osculating circle

thus the centre of the osculating circle is $(0, \pi, -2) + \frac{37}{18}(0, 0, 1) = (0, \pi, \frac{1}{18})$

and the circle lies in the plane $x + 6y = 6\pi$

the osculating circle is given by

$$C_{\pi}(\theta) = (0, \pi, \frac{1}{18}) + \cos(\theta)T(\pi) + \sin(\theta)N(\pi)$$

where $\theta \in [0, 2\pi)$