

## Genus g Zhu Recursion for Vertex Operator Algebras

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In this talk, we will outline recent work done on general genus Zhu recursion for vertex operator algebras.

We begin with a brief recap of vertex operator algebras (VOAs). A vertex operator algebra is a quadruple  $(V, Y(,), \mathbf{1}, \omega)$  consisting of the following data:

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- A vacuum vector  $\mathbf{1} \in V$
- A Virasoro vector  $\omega \in V$

This data obeys the following axioms:

• For all u, v in V, there exists an integer N such that:

$$(z-w)^N[Y(u,z),Y(v,w)]=0$$

where [,] is the commutator defined by:

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•  $Y(\mathbf{1},z) = Id_V$ 

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#### VOAs continued

Y(ω, z) = ∑<sub>n∈ℤ</sub> L(n)z<sup>-n-2</sup> where the L(n) operators satisfy the Virasoro Lie algebra:

$$[L(m), L(n)] = (m - n)L(m + n) + \frac{m^3 - m}{12}\delta_{m, -n}c$$

where c is a parameter known as the central charge.

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• The L(0) operator induces a grading on V, i.e.

$$V = \bigoplus_{n \in \mathbb{N}} V_n$$

where  $V_n$  is given by

$$\{v \in V : L(0)v = nv, n \in \mathbb{N}\}$$

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• 
$$Y(L(-1)v,z) = \frac{d}{dz}Y(v,z)$$

In previous talks, we have mostly examined genus two Zhu recursion, building on genus one data.

The aim of this project is to find a formula for all genera, building on genus zero data using the *canonical formalism*. Define the indexing sets

$$\mathcal{I} = \{-1, \ldots, -g, 1, \ldots, g\}, \quad \mathcal{I}_+ = \{1, 2, \ldots, g\}$$

To construct a genus g surface, we begin by excising 2g discs on the sphere  $S^{(0)}$ . Let Let  $\{Q_a\}$  be a set of 2g points on  $S^{(0)}$  for  $a \in \mathcal{I}$ . Let  $z_a$  denote a local coordinate in the neighbourhood of  $Q_a$ . We introduce g sewing parameters  $\rho_a = \rho_{-a}$  and excise 2g disks

$$|z_a| < \frac{|\rho_a|}{r_{-a}}$$

for real  $r_a > 0$  to form a sphere with 2g punctures. Denote this new surface by  $\widehat{S}^{(0)}$ .

Define 2g annuli on  $\widehat{\mathcal{S}}^{(0)}$  centred at  $Q_a$  by

$$\mathcal{A}_{a} = \{|\rho_{a}|/r_{-a} \leq |z_{a}| \leq r_{a}\}$$

The construction of the genus g surfaces is completed by identifying the annuli  $A_a$  and  $A_{-a}$  using the sewing relation

$$z_a z_{-a} = \rho_a; a \in \mathcal{I}_+$$

with the stipulation that the parameters  $r_a$  are sufficiently small so as to prevent intersection of distinct annuli.

Taking the limit  $\rho_a \to 0$  for all  $a \in \mathcal{I}_+$ , we see that the genus g surface  $\mathcal{S}^{(g)}$  degenerates to the Riemann sphere  $\mathcal{S}^{(0)}$ .

#### The Canonical Formalism

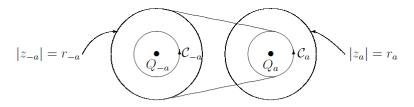


Fig 1. Sewing of annuli.

The genus zero *n*-point function is defined for states  $v_k \in V$ ,  $k = 1, \ldots n$  by

$$Z_V^{(0)}(\mathbf{v},\mathbf{y}) = \langle \mathbf{1}, \mathbf{Y}(\mathbf{v},\mathbf{y})\mathbf{1} \rangle$$

where  $\mathbf{Y}(\mathbf{v}, \mathbf{y}) = Y(v_1, y_1)Y(v_2, y_2) \dots Y(v_n, y_n)$  and  $\mathbf{1}$  denotes the vacuum vector.

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We find that the genus zero *n*-point function obeys the following recursion formula:

Theorem (Genus Zero Zhu Recursion)

For u quasiprimary of weight N, the genus zero (n + 1)-point function obeys the following Zhu recursion formula

$$Z_{V}^{(0)}(u,x;\mathbf{v},\mathbf{y}) = \sum_{k=1}^{n} \sum_{j\geq 0} \partial^{(0,j)} \zeta_{N}(x,y_{k}) Z_{V}^{(0)}(\ldots;u(j)v_{k},y_{k};\ldots).$$
(1)

where  $\partial^{(i,j)} f(x,y) = \partial^{(i)}_x \partial^{(j)}_y f(x,y)$  and  $\partial^{(i)} = \frac{1}{i!} \partial^i$ , with  $\zeta_N(x,y)$  given by

$$\zeta_N(x,y) = rac{1}{x-y} + \sum_{\ell=0}^{2N-2} f_\ell(x) y^\ell,$$

where  $f_{\ell}(x)$  is any Laurent series in x. We have found that we have a large degree of latitude in the choice of  $f_{\ell}(x)$ , however some choices are more "interesting" than others.

We now want to extend this result to any genus.

#### General Genus *n*-Point Functions

Let  $\boldsymbol{b}_+$  denote an element of a basis  $\{b_a\}$  for  $V^{\otimes g}$ , i.e. g copies of V, with  $a \in \mathcal{I}_+$ , and let  $\overline{b}_a$  denote the dual vector with respect to the  $\rho_a$ -dependent Li-Z metric  $\langle \cdot, \cdot \rangle_a$ . Now for  $\overline{b}_a \in V_{n_a}$ , define for  $a \in \mathcal{I}_+$ 

$$b_{-a} = \overline{b}_{a}$$

Now we will consider Zhu recursion for genus g n-point functions. The genus g n-point function is given by:

$$Z_V^{(g)}(\mathbf{v},\mathbf{y}) = \sum_{\mathbf{b}_+} Z_V^{(0)}(\mathbf{v},\mathbf{y};\mathbf{b},\mathbf{w}),$$

where

$$Z_V^{(0)}(\mathbf{v},\mathbf{y};\mathbf{b},\mathbf{w}) = Z_V^{(0)}(v_1,y_1;\ldots;v_n,y_n;b_{-1},w_{-1};\ldots;b_g,w_g).$$

## General Genus Zhu Recursion

#### We eventually find that

#### Theorem

Genus g Zhu Recursion The genus g n-point function for a quasiprimary vector u of weight wt(u) = N inserted at  $x \in S^{(g)}$  and general vectors  $v_1, v_2 \dots, v_n$  inserted at  $y_1, y_2 \dots, y_n \in S^{(g)}$  respectively, obeys the recursive identity

$$Z_{V}^{(g)}(u, x; \boldsymbol{v}, \boldsymbol{y}) = \phi^{(g)}(x) X^{\Pi} + \sum_{k=1}^{n} \sum_{j \ge 0} \partial^{(0,j)} \zeta_{N}^{(g)}(x, y_{k}) Z_{V}^{(g)}(\dots; u(j)v_{k}, y_{k}; \dots).$$
(2)

where  $\phi^{(g)}(x)$  is a doubly indexed row vector given by

$$\phi^{(g)}(x) = \left(A(x) + \widetilde{A}(x)\left(I - \widetilde{R}\right)^{-1}(R + \Lambda\Gamma)\right)\Pi,$$

$$\begin{split} X^{\Pi} &= (X_a^{\Pi}(m)) \text{ is given by} \\ X_a^{\Pi}(m) &= \rho_a^{-\frac{m}{2}} \sum_{\boldsymbol{b}_+} Z_V^{(0)}(\dots u(m)b_a, w_a; \dots), \\ m &= 0, \dots, 2N-2. \text{ Lastly, } \zeta_N^{(g)}(x, y) \text{ is given by} \\ \zeta_N^{(g)}(x, y) &:= \zeta_N(x, y) + \widetilde{A}(x)(I - \widetilde{R})^{-1}B(y), \end{split}$$

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## Genus g Objects

## where the following are all indexed by $a, b \in \mathcal{I}$ , $m, n \ge 0$ : $A_a(x, m) = \rho_a^{\frac{m}{2}} \partial^{(0,m)} \zeta_N(x, w_a), \quad \widetilde{A}(x) = A(x)\Delta,$

with

$$\Delta_{ab}(m,n) = \delta_{m,n+K+1}\delta_{ab},$$

similarly,

$$\Gamma_{ab}(m,n) = \delta_{m,-n+K} \delta_{a,-b},$$

and

$$R_{ab}(m,n) = \begin{cases} (-1)^N \rho_a^{\frac{m+1}{2}} \rho_b^{\frac{n}{2}} \partial^{(m,n)} \zeta_N(w_{-a},w_b), & a \neq -b, \\ 0, & a = -b. \end{cases}$$

with 
$$\widetilde{R} = R\Delta$$
 and  $\left(I - \widetilde{R}\right)^{-1} = \sum_{k \ge 0} \widetilde{R}^k$ .

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Lastly,

$$\Lambda_{ab}(m,n) = (-1)^N \rho_a^{\frac{i+j+1}{2}} \partial_{w_{-a}}^{(j)} \mathcal{F}_i(w_{-a}) \delta_{ab},$$

where  $\mathcal{F}_i$  depends on the choice of  $\{f_\ell(x)\}$  in  $\zeta_N(x, y)$ , and

$$B_{a}(y;m) = (-1)^{N} \rho_{a}^{\frac{m+1}{2}} \partial^{(m,0)} \zeta_{N}(w_{-a},y).$$

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We have found that  $\zeta_N^{(g)}(x, y)$  can be expressed as a Poincaré sum over the genus g Schottky group

$$\zeta_N^{(g)}(x,y)dx^N = \sum_{\gamma \in \Gamma_S^{(g)}} \zeta_N^{(0)}(\gamma x,y)d(\gamma x)^N$$

We believe that the vector  $\phi^{(g)}(x)$  comprises a (non-independent) spanning set of differential forms on the genus g Riemann surface.

We are currently working on constructing a normalised basis from these entries with dimension complying with the Riemann-Roch Theorem.

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