

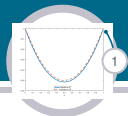


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# **A short note on 4th order real-valued singularly perturbed problems**

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Introduction

Research Question

The finite difference method

Real-valued problems

- About the boundary conditions

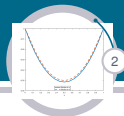
- How not to solve this problem

- A positive definite system

Example

Conclusions and future work

References



We are interested in the numerical solution of a singularly perturbed, fourth-order ordinary differential equations.

Our model differential equation is

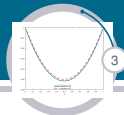
$$-\varepsilon^2 u^{(4)}(x) + au''(x) - bu(x) = f(x) \quad \text{on} \quad \Omega := (0, 1), \quad (1)$$

subject to the boundary conditions

$$u(0) = u''(0) = 0, \quad u(1) = u''(1) = 0.$$

Here  $\varepsilon$  is a positive, real-valued parameter:  $0 < \varepsilon \leq 1$ , but typically  $\varepsilon \ll 1$ . And so the problem is **singularly perturbed**.

The coefficient functions  $a$ ,  $b$  and right-hand side function  $f$  are real or complex-valued functions on the interval  $\Omega$ .

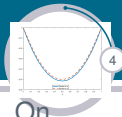


The above problem is complicated, because solutions feature **boundary layers**.

The numerical methods are used to solve this problem (1)

- ▶ By using standard **finite difference methods**, on specialised fitted meshes: the well-known piecewise uniform *Shishkin* mesh, and the more complicated *Bakhvalov* mesh.
- ▶ The numerical analysis of such method usually relies on Maximum Principles, but these do not hold, in a direct way.
- ▶ Since we cannot use standard ideas, we take the approach of rewriting (1) as a coupled system of real-valued problems, and establish that the coefficient matrix for this system is positive definite.

# The finite difference method



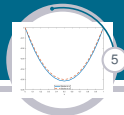
Consider an arbitrary mesh,  $\Omega^N := \{0 = x_0 < x_1 < \dots < x_N = 1\}$ . On this we define the standard second-order approximation of the second derivative

$$\delta^2 u_i := \frac{1}{\bar{h}_i} \left( \frac{u_{i-1}}{h_i} - u_i \left( \frac{1}{h_i} + \frac{1}{h_{i+1}} \right) + \frac{u_{i+1}}{h_{i+1}} \right), \quad (2)$$

and we define the standard 4th-order approximation of the fourth derivative

$$\begin{aligned} u^{(4)}(x_i) \approx D^4 u_i := & \frac{6}{(\bar{h}_{i-1} + \bar{h}_{i+1})(h_{i-1} + h_i + h_{i+1})\bar{h}_{i-1}h_{i-1}} u_{i-2} \\ & - \frac{12}{h_{i-1}(h_i + h_{i+1} + h_{i+2})\bar{h}_i h_i} u_{i-1} + \frac{6}{\bar{h}_{i-1}h_2\bar{h}_{i+1}h_3} u_i - \frac{12}{\bar{h}_i h_{i+1} h_{i+2} (h_{i-1} + h_i + h_{i+1})} u_{i+1} \\ & + \frac{6}{(\bar{h}_{i-1} + \bar{h}_{i+1})(h_i + h_{i+1} + h_{i+2})\bar{h}_{i+1}h_{i+2}} u_{i+2}, \quad (3) \end{aligned}$$

where  $h_i = x_i - x_{i-1}$  and  $\bar{h}_i = (x_{i+1} - x_{i-1})/2$ .



We consider the case of real-valued fourth-order ordinary differential equations and the following example from the literature.

[Shanthi and Ramanujam, 2002]:

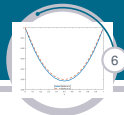
$$-\varepsilon^2 u^{(4)}(x) + au''(x) - bu(x) = f(x) \quad \text{on} \quad \Omega := (0, 1), \quad (4)$$

subject to the boundary conditions

$$u(0) = u''(0) = u(1) = u''(1) = 0.$$

The coefficient functions  $a$ ,  $b$  and right-hand side function  $f$  are real-valued functions on the interval  $\Omega$ .

# About the boundary conditions



It is important to note that the boundary conditions are

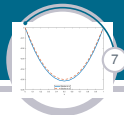
$$u(0) = u''(0) = u(1) = u''(1) = 0. \quad (5)$$

It is also common to have boundary conditions of the form

$$u(0) = u'(0) = u(1) = u'(1) = 0. \quad (6)$$

When the conditions are of the form given in (5), then the equation can be written as a system of two second order equations, and solved using techniques for such problems.

# How *not* to solve this problem



When the boundary conditions are

$$u(0) = u''(0) = u(1) = u''(1) = 0.$$

we can set  $u'' = w$  and write the problem as the following coupled system:

$$-\varepsilon^2 w'' + aw - bu = f, \quad (7a)$$

$$-u'' + w = 0, \quad (7b)$$

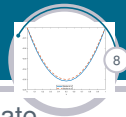
Written in matrix-vector form, this is

$$-\begin{pmatrix} \varepsilon^2 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} w'' \\ u'' \end{pmatrix} + \begin{pmatrix} a & -b \\ 1 & 0 \end{pmatrix} \begin{pmatrix} w \\ u \end{pmatrix} = \begin{pmatrix} f \\ 0 \end{pmatrix}.$$

There are numerous papers that study this formulation, but some are flawed. For example, in [Xenophontos et al., 2013a] some of the analysis depends on the coefficient matrix of the zero-order term being “**pointwise positive definite** (but not necessarily symmetric)”. But this is impossible!



# A positive definite system



We now propose an simple approach that allows one to reformulate (4) as a system with a (non-symmetric) positive definite coefficient matrix. We set

$$u'' := \alpha w + \beta u,$$

and, consequently,

$$u^{(4)} = \alpha w'' + \beta \alpha w + \beta^2 u.$$

With this, (4) can be transformed as a system of two equations of the form

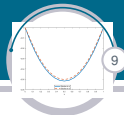
$$-\varepsilon^2 \alpha w'' + (a\alpha - \varepsilon^2 \alpha \beta) w + (a\beta - \varepsilon^2 \beta^2 - b) u = f, \quad (8a)$$

$$-u'' + \alpha w + \beta u = 0, \quad (8b)$$

subject to the boundary conditions

$$u(0) = w(0) = u(1) = w(1) = 0.$$

# Coercivity property of the matrix



Written in matrix form, this is

$$-\begin{pmatrix} \varepsilon^2 \alpha & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} w'' \\ u'' \end{pmatrix} + B \begin{pmatrix} w \\ u \end{pmatrix} = \begin{pmatrix} f \\ 0 \end{pmatrix}.$$

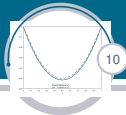
where

$$B = \begin{pmatrix} a\alpha - \varepsilon^2 \alpha \beta & a\beta - \varepsilon^2 \beta^2 - b \\ \alpha & \beta \end{pmatrix}.$$

Our eventual goal is to analyse the convergence of a finite difference scheme for this problem. We wish to apply the analysis techniques from [Bakhvalov, 1969, Kellogg et al., 2008], for which we need that

$$\mathbf{v}^T B \mathbf{v} \geq \delta \mathbf{v}^T \mathbf{v},$$

for all vectors  $\mathbf{v}$ , and some positive constant  $\delta$ .



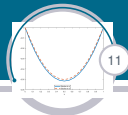
This  $B$  satisfies  $\mathbf{v}^T B \mathbf{v} \geq \delta \mathbf{v}^T \mathbf{v}$ , for all  $\mathbf{v}$ , if and only if,  $M = (B^T + B)/2$  is symmetric positive definite. Here

$$M = \begin{pmatrix} \mathbf{a}\alpha - \varepsilon^2\alpha\beta & \frac{1}{2}(\mathbf{a}\beta - \varepsilon^2\beta^2 - \mathbf{b} + \alpha) \\ \frac{1}{2}(\mathbf{a}\beta - \varepsilon^2\beta^2 - \mathbf{b} + \alpha) & \beta \end{pmatrix}.$$

Clearly,  $M$  is symmetric. In addition  $M$  is positive definite if and only if all of its eigenvalues are positive [Horn et al., 1990, Thm 7.2.1]. That will be the case if  $M$  is *strictly diagonally dominant*, with positive diagonal entries, i.e.,  $M_{ii} > \sum_{j \neq i} |M_{ij}|$  for  $i = 1, 2$  [Beezer, 2008]. So, thus, we require that

- (i)  $|\mathbf{a}\alpha - \varepsilon^2\alpha\beta| > 0$ ,
- (ii)  $|\beta| > 0$ ,
- (iii)  $|\mathbf{a}\alpha - \varepsilon^2\alpha\beta| > |\frac{1}{2}(\mathbf{a}\beta - \varepsilon^2\beta^2 - \mathbf{b} + \alpha)|$ ,
- (iv)  $|\beta| > |\frac{1}{2}(\mathbf{a}\beta - \varepsilon^2\beta^2 - \mathbf{b} + \alpha)|$ .

# Example



Now consider the real-valued problem:

$$-\varepsilon^2 u^{(4)}(x) + 2u''(x) - 4u(x) = f(x) \quad \text{on} \quad \Omega := (0, 1), \quad (9)$$

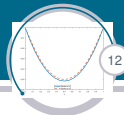
subject to the boundary conditions

$$u(0) = u''(0) = 0, \quad u(1) = u''(1) = 0.$$

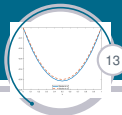
If we take  $\alpha = 1$  and  $\beta = 1$ , we have

$$B = \begin{pmatrix} 2 - \varepsilon^2 & -(\varepsilon^2 + 2) \\ 1 & 1 \end{pmatrix}, \quad \text{and} \quad M = \begin{pmatrix} 2 - \varepsilon^2 & -\frac{1}{2}(\varepsilon^2 + 1) \\ -\frac{1}{2}(\varepsilon^2 + 1) & 1 \end{pmatrix}.$$

where  $M$  is a symmetric positive definite for  $\varepsilon < \sqrt{2}$ .



- ▶ We have shown that standard ideas cannot be used for this problem.
- ▶ We are now working on the analysis of methods for **fourth-order complex-valued** problems in the case where the problem can be re-cast as a coupled system of second-order problems (see, e.g., [Xenophontos et al., 2013b]).
- ▶ We also aim to extend the work to complex-valued fourth-order ones which **cannot** be written as a coupled system of second-order ones (e.g., [Constantinou et al., 2016]).



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A large, stylized blue water splash graphic with the text "Thank you" centered inside it. The splash is composed of various droplets and streams of water, creating a dynamic and fluid appearance. The text is in a simple, black, sans-serif font.

Thank you